

Math

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots = \sum_{i=0}^{\infty} \frac{x^i}{i!}$$

$$e^{-x} = 1 - x + \frac{x^2}{2!} - \frac{x^3}{3!} + \dots = \sum_{i=0}^{\infty} \frac{(-x)^i}{i!}$$

$$\frac{e^x + e^{-x}}{2} = 1 + \frac{x^2}{2!} + \frac{x^4}{4!} + \dots = \sum_{i=0}^{\infty} \frac{(x)^{2i}}{(2i)!}$$

- $f(t_1, t_2) = f(t_1 + \delta, t_2 + \delta) \quad \forall \delta \rightarrow f(t_1 - t_2)$

- Addition formulas

$$\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B$$

$$\cos(A \pm B) = \cos A \cos B \mp \sin A \sin B$$

$$\tan(A \pm B) = \frac{\tan A \pm \tan B}{1 \mp \tan A \tan B}$$

$$\cot(A \pm B) = \frac{\cot A \cot B \mp 1}{\cot B \pm \cot A}$$

- Sum, difference and product of trigonometry function

$$\sin A + \sin B = 2 \sin\left(\frac{A+B}{2}\right) \cos\left(\frac{A-B}{2}\right)$$

$$\sin A - \sin B = 2 \cos\left(\frac{A+B}{2}\right) \sin\left(\frac{A-B}{2}\right)$$

$$\cos A + \cos B = 2 \cos\left(\frac{A+B}{2}\right) \cos\left(\frac{A-B}{2}\right)$$

$$\cos A - \cos B = 2 \sin\left(\frac{A+B}{2}\right) \sin\left(\frac{A-B}{2}\right)$$

$$\sin A \sin B = \frac{1}{2} (\cos(A-B) - \cos(A+B))$$

$$\cos A \cos B = \frac{1}{2} (\cos(A-B) + \cos(A+B))$$

$$\sin A \cos B = \frac{1}{2} (\sin(A-B) - \sin(A+B))$$

Revision

- Cauchy-Schwarz Inequality : $(EXY)^2 \leq EX^2 EY^2$

Proof:

$$\text{Let } Q(I) = E(X - IY)^2 = EX^2 - 2IEXY + I^2EY^2 \geq 0$$

Let $\min Q(\lambda)$ occurs at λ_0 , then

$$\frac{d}{dI}Q(I) = -2EXY + 2IEY^2 = 0 \Rightarrow I_0 = \frac{EXY}{EY^2}$$

$$Q(I_0) = EX^2 - 2\frac{EXY}{EY^2}EXY + \left(\frac{EXY}{EY^2}\right)^2 EY^2 = \frac{1}{EY^2}(EX^2EY^2 - (EXY)^2)$$

If $Q(\lambda_0) > 0$, then $\frac{1}{EY^2}(EX^2EY^2 - (EXY)^2) > 0 \Rightarrow EX^2EY^2 > (EXY)^2$

If $Q(\lambda_0) = 0$, then $\frac{1}{EY^2}(EX^2EY^2 - (EXY)^2) = 0 \Rightarrow EX^2EY^2 = (EXY)^2$

- X and Y are uncorrelated iff $EXY = EX EY$

- $Y = g(X) \rightarrow f_{Y_t}(y) = \left| \frac{d}{dy}g^{-1}(y) \right| f_{X_t}(g^{-1}(y))$

Random Process

- $X(t, \omega) \triangleq \{X_t, t \in T\}$
 - If we fix the value of t, say as t' , then we get random variable $X_{t'}(s) = X(t', s)$
 - If we fix the value of s, say as s' , then we get the **sample function**
 $X_{s'}(t) = X(t, s')$

Covariance and Correlation Function

- **autocorrelation function** of the random process $\{X_t\}$

$$R_X(t_1, t_2) = E[X_{t_1} X_{t_2}]$$

- cross-correlation function

$$R_{XY}(t_1, t_2) = E[X_{t_1} Y_{t_2}]$$

- **covariance function** of the random process $\{X_t\}$

$$K_X(t_1, t_2) = \text{cov}(X_{t_1}, X_{t_2})$$

- $= E((X_{t_1} - EX_{t_1})(X_{t_2} - EX_{t_2})) = EX_{t_1}X_{t_2} - EX_{t_1}EX_{t_2}$

- $= R_X(t_1, t_2) - E[X_{t_1}]E[X_{t_2}]$

- $K_{XY}(t_1, t_2) = \text{cov}(X_{t_1}, Y_{t_2})$

- $= R_{XY}(t_1, t_2) - E[X_{t_1}]E[Y_{t_2}]$

Example

- $X_i \sim \text{bernoulli}(p)$, i.i.d.

- $EX = p(1) + (1-p)(0) = p$
- $EX^2 = p(1)^2 + (1-p)0^2 = p$
- $\text{VAR}(X) =$
 - $E(X-EX)^2 = p(1-p)^2 + (1-p)(0-p)^2 = (1-p)p(1-p+p) = p(1-p)$
 - $EX^2 - (EX)^2 = p - p^2 = p(1-p)$
- $Y_j = \sum_{i=1}^j X_i$
 - $Y_i \sim \text{binomial}(i, p)$
 - $EY_n = nEX = np$
 - $EV_n^2 = E\left(\sum_{i=1}^n X_i\right)^2 = nEX^2 + \underbrace{\sum_{i \neq j} EX_i X_j}_{n^2-n \text{ terms}} = nEX^2 + (n^2 - n)(EX)^2$
 $= np + (n^2 - n)p^2 = np + n^2 p^2 - np^2$
 - $\text{VAR}(Y_n) = E(Y_n - EV_n)^2 =$
 - $n \text{ VAR}(X) = np(1-p)$
 - $EV_n^2 - (EV_n)^2 = (np + n^2 p^2 - np^2) - (np)^2 = np - np^2 = np(1-p)$
 - $\text{VAR}(Y_m - Y_n)$ where $m \neq n$
 - Observe:
 - If $m > n$,
$$Y_m - Y_n = \sum_{i=n+1}^m X_i$$
 - If $m < n$, consider $Y_n - Y_m$ instead (since $\text{VAR}(-Z) = \text{VAR}(Z)$)
 - In any case, this is the sum of $|m-n|$ different X_i , so
 $\text{VAR}(Y_m - Y_n) = |m - n| p(1-p)$
 - $\text{cov}(Y_m, Y_n)$ where $m \neq n$
$$\begin{aligned} \text{VAR}(Y_m - Y_n) &= E(Y_m - Y_n)^2 - (E(Y_m - Y_n))^2 \\ &= E(Y_m - Y_n)^2 - (EV_m - EV_n)^2 \\ &= (EV_m^2 + EV_n^2 - 2EV_m Y_n) - ((EV_m)^2 + (EV_n)^2 - 2EV_m EV_n) \\ &= (EV_m^2 - (EV_m)^2) + (EV_n^2 - (EV_n)^2) - 2(EV_m Y_n - EV_m EV_n) \\ &= \text{VAR}(Y_m) + \text{VAR}(Y_n) - 2\text{cov}(Y_m, Y_n) \end{aligned}$$

$$\begin{aligned}
& \text{cov}(Y_m, Y_n) \\
&= \frac{1}{2} (VAR(Y_m) + VAR(Y_n) - VAR(Y_m - Y_n)) \\
&= \frac{1}{2} (mp(1-p) + np(1-p) - |m-n|p(1-p)) = \frac{1}{2} p(1-p)(m+n-|m-n|) \\
&= \begin{cases} \frac{1}{2} p(1-p)(m+n-m+n) & ; \text{ if } m > n \\ \frac{1}{2} p(1-p)(m+n-n+m) & ; \text{ if } m < n \end{cases} = \begin{cases} np(1-p) & ; \text{ if } m > n \\ mp(1-p) & ; \text{ if } m < n \end{cases} \\
&= p(1-p)\min(m, n)
\end{aligned}$$

Example : **Random-telegraph process**

- Def:
 - Real random process $\{X_t, -\infty < t < +\infty\}$
 - $P\{X_t = 0\} = P\{X_t = 1\} = \frac{1}{2} \quad \forall t$
 - $P(k, \tau) = \frac{(It)^k e^{-It}}{k!} \quad \text{for } k = 0, 1, 2, \dots \sim \text{Poisson}$
 $= \text{probability that } k \text{ transversals from one value to another occur in a time interval of length } \tau$
 - $\lambda = \text{average number of transversals per unit time}$
 - Occurrence of k transversals in an interval of length τ is statistically independent of the value assumed by any particular sample function at the start of the given interval
 - $P(X_{t_1} = X_{t_2}) = P(X_{t_1} = 1 | X_{t_2} = 1) = P(X_{t_1} = 0 | X_{t_2} = 0) \sum_{\text{even } k} P(k, |t_1 - t_2|)$
 $= \frac{1}{2} (1 + e^{-2It})$
 - $EX_t = 0 \cdot \frac{1}{2} + 1 \cdot \frac{1}{2} = \frac{1}{2}$
 - $R_X(t_1, t_2) = EX_{t_1} X_{t_2}$
 $= 1 \cdot 1 \cdot P(X_{t_1} = 1, X_{t_2} = 1) + 1 \cdot 0 \cdot P(X_{t_1} = 1, X_{t_2} = 0)$
 $+ 0 \cdot 1 \cdot P(X_{t_1} = 0, X_{t_2} = 1) + 0 \cdot 0 \cdot P(X_{t_1} = 0, X_{t_2} = 0)$
 $= P(X_{t_1} = 1, X_{t_2} = 1)$

$$\begin{aligned}
&= P(X_{t_1} = 1 | X_{t_2} = 1) P(X_{t_2} = 1) = \frac{1}{2} P(X_{t_1} = 1 | X_{t_2} = 1) \\
&= \frac{1}{2} \sum_{even k} P(k, |t_1 - t_2|) = \frac{1}{2} \left(e^{-It} \frac{e^{It} + e^{-It}}{2} \right) = \frac{1}{4} (1 + e^{-2It}) \\
&= \frac{1}{4} (1 + e^{-2I|t_1 - t_2|})
\end{aligned}$$

- $K_X(t_1, t_2) = R_X(t_1, t_2) - E[X_{t_1} X_{t_2}] = R_X(t_1, t_2) - \frac{1}{4} = \frac{1}{4} e^{-2I|t_1 - t_2|}$

Stationary

- The random process $\{X_t, t \in T\}$ is **(strictly) stationary** if and only if all of the finite-dimensional probability distribution functions are invariant under shifts of the time origin.

That is

$\forall n$ (including $n = 1$), and

\forall set of time instants $\{t_i \in T, i = 1, 2, \dots, n\}$

$$F_{X_{t_1}, X_{t_2}, \dots, X_{t_n}}(x_{t_1}, x_{t_2}, \dots, x_{t_n}) = F_{X_{t_1+t}, X_{t_2+t}, \dots, X_{t_n+t}}(x_{t_1}, x_{t_2}, \dots, x_{t_n})$$

$\forall x_i, i \in \{1, 2, \dots, n\}$ and

$\forall \tau$ such that $(t_i + \tau) \in T$ for all i

- the k^{th} moment of any stationary random process is a constant function of time
 - $E[X_{t+t}^k] = E[X_t^k]$ because $F_{X_t}(x) = F_{X_{t+t}}(x)$
 - However, $E(X_{t_1} X_{t_2}) = R_X(t_1, t_2) = R_X(t_1 - t_2) = R_X(t)$

- The random process $\{X_t, t \in T\}$ is **wide sense stationary** (stationary to the second order) if and only if
 - 1) $E[X_t] = E[X_t] = m_X$ and
 - 2) $R_X(t, t-\tau) = R_X(\tau)$
 - $= R_X(t+\delta, t+\delta-\tau) \forall \delta \forall t = R_X(t', t'-\tau) \forall \tau \forall t'$

- Ex. $Z_t = Y \cos(t) + X \sin(t)$

$$EY = 0$$

X, Y are independent $\Rightarrow EXY = EXEY = 0$

$$EX^2 = EY^2 = \sigma^2$$

- $EZ_t = \cos(t)EY + \sin(t)EX = 0$

- $R_Z(t_1, t_2)$

$$\begin{aligned}
&= EZ_{t_1} Z_{t_2} = E(Y \cos(t_1) + X \sin(t_1))(Y \cos(t_2) + X \sin(t_2)) \\
&= (EY^2)\cos(t_1)\cos(t_2) + (EX^2)\sin(t_1)\sin(t_2) \\
&\quad + (\cancel{EXY})(\cos(t_1)\sin(t_2) + \sin(t_1)\cos(t_2)) \\
&= (EY^2)\cos(t_1)\cos(t_2) + (EX^2)\sin(t_1)\sin(t_2) \\
&= s^2(\cos(t_1)\cos(t_2) + \sin(t_1)\sin(t_2)) = s^2 \cos(t_1 - t_2)
\end{aligned}$$

- Z_t is stationary in the wide sense, since EZ_t is constant with time, and $R_z(t_1, t_2)$ depends only on the time difference $\tau = t_1 - t_2$.
- Not strictly stationary since EZ_t^3 depends on time.

- $R_X(-\tau) = R_X(\tau)$

Proof:

$$\begin{aligned}
R_X(\tau) &= R_X(t, t-\tau) \\
R_X(-\tau) &= R_X(t, t-(-\tau)) = R_X(t, t+\tau) = EX_t X_{t+\tau} = EX_{t+\tau} X_t = R_X(t+\tau, t) \\
&= R_X(t+\tau-t, t-\tau) ; \text{ from w.s.s.} \\
&= R_X(t, t-\tau)
\end{aligned}$$

- $|R_X(t)| \leq EX_t^2 = R_X(0)$

Proof :

Cauchy-Schwarz Inequality : $(EXY)^2 \leq EX^2 EY^2$

$$\begin{aligned}
(R_X(t))^2 &= (EX_t X_{t-t})^2 \leq EX_t^2 EX_{t-t}^2 \stackrel{w.s.s.}{=} EX_t^2 EX_t^2 = (EX_t^2)^2 \\
(R_X(t))^2 &\leq (EX_t^2)^2 \Rightarrow |R_X(t)| \leq |EX_t^2| = EX_t^2
\end{aligned}$$

- If $R_X(\tau)$ of a given process is continuous at $\tau = 0$, then it is also continuous at every other value of τ .

- If $R_X(T) = R_X(0)$, then

- $X_{t+T} = X_t \forall t$

Proof

$$\begin{aligned}
E(|X_{t+T} - X_t|^2) &= EX_{t+T} X_{t+T} + EX_t X_t - 2EX_{t+T} X_t \\
&= R_X(0) + R_X(0) - 2R_X(0) = 0
\end{aligned}$$

$\leadsto X_t = X_{t+T}$

- Process is periodic with period T $R_X(\tau+T) = R_X(\tau)$

Proof: $R_X(t+T) = EX_{t+t+T} X_t = EX_{(t+t)+T} X_t = EX_{t+T} X_t = R_X(t)$

- The random process $\{X_t, t \in T\}$ is **covariance stationary** if and only if

$$K_X(t, t-t) = K_X(t', t'-t) \forall t = K_X(t)$$

- strictly stationary \rightarrow wide sense stationary \rightarrow covariance stationary

- converse does not necessarily hold true

- Proof: strictly stationary \rightarrow wide sense stationary

- $n = 1: f_{X_t}(x) = f_{X_{t+\tau}}(x) \forall \tau$

$$EX_{t+\tau} = \int_{-\infty}^{\infty} xf_{X_{t+\tau}}(x)dx = \int_{-\infty}^{\infty} xf_{X_t}(x)dx = EX_t = m_X$$

- $n = 2: f_{X_{t_1}, X_{t_2}}(x_1, x_2) = f_{X_{t_1+d}, X_{t_2+d}}(x_1, x_2) ; \forall d, \forall t_1, \forall t_2$

$$\begin{aligned} R_X(t_1 + d, t_2 + d) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1 x_2 f_{X_{t_1+d}, X_{t_2+d}}(x_1, x_2) dx_1 dx_2 \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1 x_2 f_{X_{t_1}, X_{t_2}}(x_1, x_2) dx_1 dx_2 = R_X(t_1, t_2); \forall d \end{aligned}$$

$$\therefore R_X(t_1, t_2) = R_X(t_1 - t_2) = R_X(t)$$

- Proof: wide sense stationary \rightarrow covariance stationary

$$K_X(t_1, t_2) = R_X(t_1, t_2) - (EX_{t_1})(EX_{t_2}) = R_X(t_1 - t_2) - m_X^2$$

$$\therefore K_X(t_1, t_2) = K_X(t_1 - t_2) = K_X(t)$$

- **If $\{X(t)\}$ is strictly stationary, then $\{Y(t)\} = \{g(X(t))\}$ is strictly stationary**

- proof:

Consider finite-dimensional $F_{Y(t)}(\underline{y})$

$$F_{Y(t)}(\underline{y}) = P(Y(t) \leq \underline{y}) = P(g(\underline{X}(t)) \leq \underline{y}) = P(\underline{X}(t) \in \{\underline{X} : g(\underline{X}) \leq \underline{y}\})$$

where \underline{Y} , \underline{t} , \underline{y} , \underline{X} , \underline{x} are all n-dimensional vectors.

Since $\{X(t)\}$ is strictly stationary,

for any $\underline{d} = (\underbrace{\underline{d}, \underline{d}, \dots, \underline{d}}_{n\text{-dimension}})$,

$$P(\underline{X}(t) \in \{\underline{X} : g(\underline{X}) \leq \underline{y}\}) = P(\underline{X}(t + \underline{d}) \in \{\underline{X} : g(\underline{X}) \leq \underline{y}\})$$

Therefore,

$$\begin{aligned} F_{Y(t)}(\underline{y}) &= P(\underline{X}(t + \underline{d}) \in \{\underline{X} : g(\underline{X}) \leq \underline{y}\}) \\ &= P(g(\underline{X}(t + \underline{d})) \leq \underline{y}) = P(Y(t + \underline{d}) \leq \underline{y}) \\ &= F_{Y(t+\underline{d})}(\underline{y}) \text{ for any } \underline{y}, \underline{t}, \underline{\delta} \end{aligned}$$

- proof for wide sense stationary

$$E[Y(t)] = E[g(X(t))] = \int_{-\infty}^{\infty} g(x) f_{X(t)}(x) dx \text{ and}$$

$$R_Y(t_1, t_2) = E[g(X(t_1))g(X(t_2))] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x_1)g(x_2)f_{X(t_1), X(t_2)}(x_1, x_2)dx_1 dx_2$$

Since $\{X(t)\}$ is strictly stationary,

$$f_{X(t)}(x) = f_{X(t+\delta)}(x)$$

$$f_{X(t_1), X(t_2)}(x_1, x_2) = f_{X(t_1+\delta), X(t_2+\delta)}(x_1, x_2)$$

for any t, t_1, t_2, δ

So,

$$E[Y(t)] = E[Y(t+\delta)] \text{ for any } t, \delta$$

$$\Rightarrow E[Y(t)] = \text{constant for all } t$$

$$R_Y(t_1, t_2) = R_Y(t_1 + \delta, t_2 + \delta) \text{ for any } t_1, t_2, \delta$$

$$\Rightarrow R_Y(t, t - \tau) = R_Y(\tau) \text{ for any } t \text{ and } \tau$$

Example

$\{X_k, k = 1, 2, \dots\}$ is collection of i.i.d. $\mathcal{N}(0, \sigma^2)$ r.v.

$\{T_i, i = 1, 2, \dots\}$ is a collection of i.i.d. exponential r.v. whose common p.d.f. is

$$f_T(t) = e^{-t}, t \geq 0$$

$\{T_i, i = 1, 2, \dots\}$ is independent of $\{X_k\}$

Let $S_0 = 0$ and $S_k = T_1 + \dots + T_k$ for $k \geq 1$.

The time-continuous r.p. $\{Z_t, t \geq 0\}$ is defined by $Z_t = X_k$ for $S_{k-1} \leq t < S_k$.

That is, Z_t stays at the value X_1 over the time interval $[0, T_1]$,

then jumps to the value X_2 at which it stays for the next T_2 seconds,

then jumps to X_3 and stays there for the next T_3 seconds, and so on.

- $m_Z(t) = 0$

$$EZ_t = \sum_{k=1}^{\infty} P(S_{k-1} \leq t < S_k) EX_k = \sum_{k=1}^{\infty} P(S_{k-1} \leq t < S_k) EX$$

$$= EX \sum_{k=1}^{\infty} P(S_{k-1} \leq t < S_k) = EX = 0$$

- $R_Z(t, s) = \sigma^2 e^{-|s-t|}$

- Exponential distribution has no memory: $P(T_k > a+b | T_k > a) = P(T_k > b)$

for $a > 0, b > 0$

$$P(T_k > a+b | T_k > a) = \frac{P(T_k > a+b, T_k > a)}{P(T_k > a)} = \frac{P(T_k > a+b)}{P(T_k > a)} = \frac{e^{-(a+b)}}{e^{-a}} = e^{-b}$$

$$P(T_k > b) = e^{-b}$$

- Consider the probability that t and s fall into same interval = p_0

- When $t \leq s$, t must falls into some interval, says $S_{k-1} \leq t < S_k$

$$\begin{aligned} p_0 &= P(S_{k-1} \leq s < S_k | S_{k-1} \leq t < S_k) \\ &= P(S_k - S_{k-1} > s - S_{k-1}, s > S_{k-1} | S_k - S_{k-1} > t - S_{k-1}, t > S_{k-1}) \end{aligned}$$

$s \geq t$, so $t > S_{k-1} \rightarrow s > S_{k-1}$

$$\begin{aligned} p_0 &= P(T_k > s - S_{k-1} | T_k > t - S_{k-1}) = P(T_k > s - t + t - S_{k-1} | T_k > t - S_{k-1}) \\ &= P\left(T_k > \underbrace{(s-t)}_b + \underbrace{(t-S_{k-1})}_a | T_k > t - \underbrace{S_{k-1}}_a\right) = P(T_k > s - t) = e^{-(s-t)} \end{aligned}$$

- When $t > s$, $p_0 = P(T_k > t - s) = e^{-(t-s)}$.
- $p_0 = e^{-|s-t|}$
- When t and s fall into same interval, $Z_t = Z_s$ says $= X_k$.

This occurs with probability p_0 .

When t and s are in different interval, $Z_t \neq Z_s$ says $Z_t = X_{k'}, Z_s = X_{k''}$.

This occurs with probability $1-p_0$.

$$\begin{aligned} R_Z(t, s) &= EZ_t Z_s = p_0 E(X_k X_k) + (1-p_0) EX_{k'} X_{k''} \\ &= p_0 EX_k^2 + (1-p_0) \underbrace{EX_{k'} EX_{k''}}_{\text{from independence}} = p_0 (s_X^2 + \sigma_X^2) = p_0 s_X^2 = s^2 e^{-|s-t|} \end{aligned}$$

- $\{Z_t\}$ is strictly stationary in the sense that $\{z_t\}$ and $\{W_t\}$ share identical joint distributions, where $W_t = Z_{t+\Delta}$ for any nonnegative time shift Δ .

Consider n-dimensional joint c.d.f. of $\{Z_{t_i}, t = 1, 2, \dots, n\}$

$$F_{Z_{t_1}, Z_{t_2}, \dots, Z_{t_n}}(z_1, z_2, \dots, z_n)$$

We can always decompose it as summation of multiplication of one-dimentional p.d.f

For example, when $n=2$

$$F_{Z_{t_1}, Z_{t_2}}(z_1, z_2) = p_0 F_{X_k}(\min(z_1, z_2)) + (1-p_0) F_{X_j}(z_1) F_{X_k}(z_2); j \neq k$$

where $p_0 = \text{probability that no jump within } (t_1, t_2) \text{ or } (t_2, t_1) = e^{-|t_1 - t_2|}$.

Since $\{X_t\}$ is i.i.d., all one dimensional p.d.f. are the same.

So, joint p.d.f. of $\{Z_{t_i}, t = 1, 2, \dots, n\}$ is dependent on $f_X(x)$ and the relation between t_a, t_b

We knows that t_a, t_b fall into the same interval or not only depends on the difference between t_a and t_b (Because T_k is exponential distributed.)

Thus, when we shift t_i to $t_{i+\delta} \forall i, i = 1, 2, \dots, n$, the difference between and two t_a, t_b stays the same, i.e. the probability that t_a, t_b are in the same interval is unchanged.

$$\text{Therefore, } F_{Z_{t_1}, Z_{t_2}, \dots, Z_{t_n}}(z_1, z_2, \dots, z_n) = F_{Z_{t_1+d}, Z_{t_2+d}, \dots, Z_{t_n+d}}(z_1, z_2, \dots, z_n).$$

- Z_t is a gaussian random variable.

$$f_{Z_t}(z) = \sum_{k=1}^{\infty} \left(P(S_{k-1} \leq t < S_k) f_{X_k}(z) \right) = \sum_{k=1}^{\infty} \left(P(S_{k-1} \leq t < S_k) f_X(z) \right)$$

$$= f_X(z) \sum_{k=1}^{\infty} P(S_{k-1} \leq t < S_k) = f_X(z)$$

- $\{Z_t\}$ is not a gaussian random process.

If Z_{t_1}, Z_{t_2} are jointly gaussian,

$$\Lambda = \begin{bmatrix} \mathbf{s}^2 & \text{cov}(Z_{t_1}, Z_{t_2}) \\ \text{cov}(Z_{t_1}, Z_{t_2}) & \mathbf{s}^2 \end{bmatrix} = \begin{bmatrix} \mathbf{s}^2 & \mathbf{s}^2 e^{-|t_1-t_2|} \\ \mathbf{s}^2 e^{-|t_1-t_2|} & \mathbf{s}^2 \end{bmatrix} = \mathbf{s}^2 \begin{bmatrix} 1 & e^{-|t_1-t_2|} \\ e^{-|t_1-t_2|} & 1 \end{bmatrix}$$

$$\text{cov}(Z_{t_1}, Z_{t_2}) = E(Z_{t_1} Z_{t_2}) - \cancel{E}Z_{t_1} \cancel{E}Z_{t_2} = E(Z_{t_1} Z_{t_2}) = R_Z(t_1, t_2) = \mathbf{s}^2 e^{-|t_1-t_2|}$$

$$\Phi_{Z_{t_1}, Z_{t_2}}(v_1, v_2) = e^{-\frac{v^T}{2} \Lambda v} = e^{-\frac{\mathbf{s}^2}{2} (v_1^2 + v_2^2 + 2v_1 v_2 e^{-|t_1-t_2|})}$$

However

$$\begin{aligned} \Phi_{Z_{t_1}, Z_{t_2}}(v_1, v_2) &= Ee^{j(v_1 Z_{t_1} + v_2 Z_{t_2})} = p_0 Ee^{j(v_1 X_k + v_2 X_k)} + (1-p_0) Ee^{j(v_1 X_k' + v_2 X_k')} \\ &= p_0 Ee^{j(v_1 + v_2) X_k} + (1-p_0) Ee^{jv_1 X_k'} Ee^{jv_2 X_k'} \\ &= p_0 \Phi_X(v_1 + v_2) + (1-p_0) \Phi_X(v_1) \Phi_X(v_2) \\ &= p_0 e^{-\frac{(v_1 + v_2)^2 \mathbf{s}^2}{2}} + (1-p_0) e^{-\frac{v_1^2 \mathbf{s}^2}{2}} e^{-\frac{v_2^2 \mathbf{s}^2}{2}} \\ &= e^{-|t_1-t_2|} e^{-\frac{(v_1 + v_2)^2 \mathbf{s}^2}{2}} + (1 - e^{-|t_1-t_2|}) e^{-\frac{v_1^2 \mathbf{s}^2}{2}} e^{-\frac{v_2^2 \mathbf{s}^2}{2}} \end{aligned}$$

$\Phi_{Z_{t_1}, Z_{t_2}}(v_1, v_2)$ does not have the form of jointly gaussian characteristic function. So, $\{Z_t\}$ is not a gaussian random process.

Gaussian Random Variable

- gaussian random variable X with mean m and variance σ^2 :

$$f_X(x) = \frac{1}{\sqrt{2\pi}\mathbf{s}} e^{-\frac{(x-m)^2}{2\mathbf{s}^2}}$$

- random variables X_1, X_2, \dots, X_n are jointly gaussian random variables iff

$$f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) = \frac{1}{(2\mathbf{s})^n |\Lambda|^{\frac{1}{2}}} e^{-\frac{1}{2|\Lambda|} \sum_{i=1}^n \sum_{j=1}^n |\Lambda|_{ij} (x_i - m_i)(x_j - m_j)}$$

where

$$m_i = EX_{t_i}; i = 1, 2, \dots, n$$

$$\Lambda = \text{covariance matrix} = (\mathbf{I}_{ij})_{n \times n} = \left(\text{cov}(X_{t_i}, X_{t_j}) \right)_{n \times n} = \left(K_X(t_i, t_j) \right)_{n \times n}$$

$|\Lambda|_{ij}$ = cofactor of the element λ_{ij} in the determinant $|\Lambda|$

Assumed that Λ is nonsingular

- X_1 and X_2 are jointly Gaussian random variables, if and only if

$$f_{X_1, X_2}(x_1, x_2) = \frac{1}{2\mathbf{p}\mathbf{s}_{X_1}\mathbf{s}_{X_2}\sqrt{1-\mathbf{r}^2}} e^{-\frac{\left(\frac{x_1-EX_1}{\mathbf{s}_{X_1}}\right)^2 - 2\mathbf{r}\left(\frac{x_1-EX_1}{\mathbf{s}_{X_1}}\right)\left(\frac{x_2-EX_2}{\mathbf{s}_{X_2}}\right) + \left(\frac{x_2-EX_2}{\mathbf{s}_{X_2}}\right)^2}{2(1-\mathbf{r}^2)}},$$

where $\mathbf{r} = \frac{\text{Cov}(X_1, X_2)}{\mathbf{s}_{X_1}\mathbf{s}_{X_2}} = \frac{E(X_1X_2) - EX_1EX_2}{\mathbf{s}_{X_1}\mathbf{s}_{X_2}}$

- If $EX_1 = EX_2 = 0$ and $\mathbf{s}_{X_1} = \mathbf{s}_{X_2} = \mathbf{s}$

$$f_{X_1, X_2}(x_1, x_2) = \frac{1}{2\mathbf{p}\mathbf{s}^2\sqrt{1-\mathbf{r}^2}} e^{-\frac{x_1^2 - 2\mathbf{r}x_1x_2 + x_2^2}{2\mathbf{s}^2(1-\mathbf{r}^2)}}$$

$$\mathbf{r} = \frac{E(X_1X_2)}{\mathbf{s}^2} = \frac{R_X(t)}{\mathbf{s}^2}$$

- If $\text{Cov}(X_1, X_2) = 0$ (or $X_1 \perp\!\!\!\perp X_2$ which also make $\text{Cov}(X_1, X_2) = 0$)

$$f_{X_1, X_2}(x_1, x_2) = f_{X_1}(x_1) \times f_{X_2}(x_2) = \frac{1}{2\mathbf{p}\mathbf{s}_{X_1}\mathbf{s}_{X_2}} e^{-\frac{\left(\frac{x_1-EX_1}{\mathbf{s}_{X_1}}\right)^2 + \left(\frac{x_2-EX_2}{\mathbf{s}_{X_2}}\right)^2}{2}}$$

$$\text{Cov}(X_1, X_2) = 0 \rightarrow \rho = 0$$

$$f_{X_1, X_2}(x_1, x_2) = \frac{1}{2\mathbf{p}\mathbf{s}_{X_1}\mathbf{s}_{X_2}\sqrt{1-\mathbf{r}^2}} e^{-\frac{\left(\frac{x_1-EX_1}{\mathbf{s}_{X_1}}\right)^2 - 2\mathbf{r}\left(\frac{x_1-EX_1}{\mathbf{s}_{X_1}}\right)\left(\frac{x_2-EX_2}{\mathbf{s}_{X_2}}\right) + \left(\frac{x_2-EX_2}{\mathbf{s}_{X_2}}\right)^2}{2(1-\mathbf{r}^2)}}$$

$$= \frac{1}{2\mathbf{p}\mathbf{s}_{X_1}\mathbf{s}_{X_2}} e^{-\frac{\left(\frac{x_1-EX_1}{\mathbf{s}_{X_1}}\right)^2 + \left(\frac{x_2-EX_2}{\mathbf{s}_{X_2}}\right)^2}{2}}$$

$$= f_{X_1}(x_1) \times f_{X_2}(x_2)$$

Gaussian Random Process

- A real random process $\{X_t\}$ is a **gaussian random process** if and only if for every n (given any arbitrary set of n time instants t_1, t_2, \dots, t_n in the index set T),

the random variable $X_{t_1}, X_{t_2}, \dots, X_{t_n}$

- are jointly gaussian random variables
 - form the components of an n-dimensional gaussian random vector
- **If a real gaussian random process is w.s.s., then it is also s.s.**

Proof:

From w.s.s.,

$$EX_{t_i} = m_j = m \text{ constant}$$

$$K_X(t_i, t_j) = R_X(t_i, t_j) - EX_{t_i}EX_{t_j} = R_X(t_i - t_j) - m^2$$

$$f_{X_{t_1}, X_{t_2}, \dots, X_{t_n}}(x_1, x_2, \dots, x_n) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Lambda|^{\frac{1}{2}}} e^{-\frac{1}{2|\Lambda|} \sum_{i=1}^n \sum_{j=1}^n |\Lambda|_{ij} (x_i - m_i)(x_j - m_j)}$$

$$\text{Then, } f_{X_{t_1}, X_{t_2}, \dots, X_{t_n}}(x_{t_1}, x_{t_2}, \dots, x_{t_n}) = f_{X_{t_1+t}, X_{t_2+t}, \dots, X_{t_n+t}}(x_{t_1}, x_{t_2}, \dots, x_{t_n})$$

- **Bussgang's Theorem**

Input: $\{X(t)\}$ is a **zero-mean stationary Gaussian random process**.

Output: $\{Y(t)\}$ is defined by $Y(t) = g(X(t))$

$g(\cdot)$ is an instantaneous nonlinear device (i.e., an ordinary real-valued function of a real variable).

→

- $\{Y(t)\}$ is not necessarily Gaussian.
- $\{Y(t)\}$ is a strictly stationary random process
- $R_{XY}(\tau) = C R_X(\tau)$, where $C = \frac{1}{s^2} E(X_t \cdot g(X_t))$ constant not depends on τ

⇒ If the input to an instantaneous nonlinear device is a stationary Gaussian random process, then the crosscorrelation function of the input and output is proportional to the auto correlation function of the input

Proof:

X_1 and X_2 are jointly Gaussian random variables, if and only if

$$f_{X_{t_1}, X_{t_2}}(x_1, x_2) = \frac{1}{2\pi s_{X_1} s_{X_2} \sqrt{1-r^2}} e^{-\frac{\left(\frac{x_1-EX_1}{s_{X_1}}\right)^2 - 2r\left(\frac{x_1-EX_1}{s_{X_1}}\right)\left(\frac{x_2-EX_2}{s_{X_2}}\right) + \left(\frac{x_2-EX_2}{s_{X_2}}\right)^2}{2(1-r^2)}},$$

$$\text{where } r = \frac{Cov(X_1, X_2)}{s_{X_1} s_{X_2}} = \frac{E(X_1 X_2) - EX_1 EX_2}{s_{X_1} s_{X_2}}$$

In this problem,

$$EX_1 = EX_2 = 0$$

$$\text{From stationarity, } s_{X_1} = s_{X_2} = s$$

$$\begin{aligned}
f_{X_1, X_2}(x_1, x_2) &= \frac{1}{2\mathbf{p}\mathbf{s}^2\sqrt{1-\mathbf{r}^2}} e^{-\frac{x_1^2 - 2\mathbf{r}x_1x_2 + x_2^2}{2\mathbf{s}^2(1-\mathbf{r}^2)}} \\
\mathbf{r} &= \frac{E(X_1 X_2)}{\mathbf{s}^2} = \frac{R_X(\mathbf{t})}{\mathbf{s}^2} \\
R_{X,Y}(t_1, t_2) &= E(X_{t_1}, Y_{t_2}) = E(X_{t_1}, g(X_{t_2})) \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1 g(x_2) f_{X_1, X_2}(x_1, x_2) dx_1 dx_2 \\
&= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} x_1 g(x_2) \frac{1}{2\mathbf{p}\mathbf{s}^2\sqrt{1-\mathbf{r}^2}} e^{-\frac{x_1^2 - 2\mathbf{r}x_1x_2 + x_2^2}{2\mathbf{s}^2(1-\mathbf{r}^2)}} dx_1 \right) dx_2 \\
&= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} x_1 g(x_2) \frac{1}{2\mathbf{p}\mathbf{s}^2\sqrt{1-\mathbf{r}^2}} e^{-\frac{(x_1 - \mathbf{r}x_2)^2 + (1-\mathbf{r}^2)x_2^2}{2\mathbf{s}^2(1-\mathbf{r}^2)}} dx_1 \right) dx_2 \\
&= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} x_1 g(x_2) \frac{1}{2\mathbf{p}\mathbf{s}^2\sqrt{1-\mathbf{r}^2}} e^{-\frac{(x_1 - \mathbf{r}x_2)^2}{2\mathbf{s}^2(1-\mathbf{r}^2)}} e^{-\frac{x_2^2}{2\mathbf{s}^2}} dx_1 \right) dx_2 \\
&= \int_{-\infty}^{\infty} g(x_2) e^{-\frac{x_2^2}{2\mathbf{s}^2}} \left(\frac{\sqrt{2\mathbf{p}}\sqrt{\mathbf{s}^2(1-\mathbf{r}^2)}}{2\mathbf{p}\mathbf{s}^2\sqrt{1-\mathbf{r}^2}} \int_{-\infty}^{\infty} x_1 \underbrace{\frac{1}{\sqrt{2\mathbf{p}}\sqrt{\mathbf{s}^2(1-\mathbf{r}^2)}} e^{-\frac{(x_1 - \mathbf{r}x_2)^2}{2(\mathbf{s}^2(1-\mathbf{r}^2))}} dx_1}_{\text{Gaussian } m' = \mathbf{r}x_2, \mathbf{s}'^2 = \mathbf{s}^2(1-\mathbf{r}^2)} \right) dx_2 \\
&= \int_{-\infty}^{\infty} g(x_2) e^{-\frac{x_2^2}{2\mathbf{s}^2}} \left(\frac{1}{\sqrt{2\mathbf{p}\mathbf{s}}} \mathbf{r}x_2 \right) dx_2 = \mathbf{r} \int_{-\infty}^{\infty} x_2 g(x_2) \frac{1}{\sqrt{2\mathbf{p}\mathbf{s}}} e^{-\frac{x_2^2}{2\mathbf{s}^2}} dx_2 \\
&= R_X(\mathbf{t}) \frac{1}{\mathbf{s}^2} \int_{-\infty}^{\infty} x_2 g(x_2) \frac{1}{\sqrt{2\mathbf{p}\mathbf{s}}} e^{-\frac{x_2^2}{2\mathbf{s}^2}} dx_2
\end{aligned}$$

$$\text{Therefore, } C = \frac{1}{\mathbf{s}^2} \int_{-\infty}^{\infty} x_2 g(x_2) \frac{1}{\sqrt{2\mathbf{p}\mathbf{s}}} e^{-\frac{x_2^2}{2\mathbf{s}^2}} dx_2 = \frac{1}{\mathbf{s}^2} E(X_t \cdot g(X_t))$$

- A w.s.s. (strictly stationary) continuous-time Gaussian r.p. $X(t)$ is Markovian if and only if $K_X(\mathbf{t}) = K_X(0) e^{-\alpha|t|}$, where α is real and positive

- For 0-mean, can use $R_X(t) = R_X(0)e^{-a|t|}$

Linear Transformation

Linear transformations on finite-dimensional random vectors

- $\underline{Y} = g(\underline{X}) = g_{m \times n} \underline{X}$ where $\dim(X) = n \geq m = \dim(Y)$
 transformation g is a linear transformation iff $g(aW + bZ) = ag(W) + bg(Z)$
 where

a and b are arbitrary real constants and
 \underline{W} and \underline{Z} are arbitrary real random vectors

- General linear transformation : $Y_i = \sum_{j=1}^n g_{ij} X_j$ where $i = 1, 2, \dots, m$

- $EY_i = \sum_{j=1}^n g_{ij} EX_j$
- $\text{cov}(Y_i, Y_k) = \sum_{j=1}^n \sum_{r=1}^n g_{ij} g_{kr} \text{cov}(X_j, X_r)$
- $S_{Y_i}^2 = \text{cov}(Y_i, Y_i) = \sum_{j=1}^n \sum_{r=1}^n g_{ij} g_{ir} \text{cov}(X_j, X_r)$

- $E\underline{Y} = gEX$
- $\Lambda_Y = g\Lambda_X g^T$
 - $\Lambda_X = (\text{cov}(X_i, X_j))$
 - $\Lambda_Y = (\text{cov}(Y_i, Y_j))$

Example: Linear transformation for two-dimensional real random vector \underline{X}

$$Y_1 = g_{11}X_1 + g_{12}X_2$$

$$Y_2 = g_{21}X_1 + g_{22}X_2$$

- If g has an inverse $\begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix} \neq 0$, say $\underline{h} = (h_1, h_2)$, then

$$f_{Y_1, Y_2}(y_1, y_2) = \left| \frac{\partial(h_1, h_2)}{\partial(y_1, y_2)} \right| f_{X_1, X_2}(h_1(y_1, y_2), h_2(y_1, y_2))$$

- $EY_1 = g_{11}EX_1 + g_{12}EX_2$

- $EY_2 = g_{21}EX_1 + g_{22}EX_2$

- $$\begin{aligned}\bullet \quad \mathbf{s}_{Y_1}^2 &= g_{11}^2 \mathbf{s}_{X_1}^2 + g_{12}^2 \mathbf{s}_{X_2}^2 + 2g_{11}g_{12} \text{cov}(X_1, X_2) \\ \mathbf{s}_{Y_2}^2 &= g_{21}^2 \mathbf{s}_{X_1}^2 + g_{22}^2 \mathbf{s}_{X_2}^2 + 2g_{21}g_{22} \text{cov}(X_1, X_2)\end{aligned}$$

$$\begin{aligned}\mathbf{s}_{Y_1}^2 &= E(Y_1 - EX_1)^2 = E((g_{11}X_1 + g_{12}X_2) - (g_{11}EX_1 + g_{12}EX_2))^2 \\ &= E(g_{11}(X_1 - EX_1) + g_{12}(X_2 - EX_2))^2 \\ &= g_{11}^2 E(X_1 - EX_1)^2 + g_{12}^2 E(X_2 - EX_2)^2 \\ &\quad + 2g_{11}g_{12}E(X_1 - EX_1)(X_2 - EX_2) \\ &= g_{11}^2 \mathbf{s}_{X_1}^2 + g_{12}^2 \mathbf{s}_{X_2}^2 + 2g_{11}g_{12} \text{cov}(X_1, X_2)\end{aligned}$$
- $$\begin{aligned}\bullet \quad \text{cov}(Y_1, Y_2) &= g_{11}g_{21}(\mathbf{s}_{X_1}^2) + g_{12}g_{22}(\mathbf{s}_{X_2}^2) + (g_{11}g_{22} + g_{12}g_{21})\text{cov}(X_1, X_2) \\ EY_1Y_2 &= E(g_{11}X_1 + g_{12}X_2)(g_{21}X_1 + g_{22}X_2) \\ &= g_{11}g_{21}EX_1^2 + g_{12}g_{22}EX_2^2 + (g_{11}g_{22} + g_{12}g_{21})EX_1X_2 \\ &= g_{11}g_{21}(\mathbf{s}_{X_1}^2 + (EX_1)^2) + g_{12}g_{22}(\mathbf{s}_{X_2}^2 + (EX_2)^2) \\ &\quad + (g_{11}g_{22} + g_{12}g_{21})(\text{cov}(X_1, X_2) + EX_1EX_2) \\ EY_1EY_2 &= (g_{11}EX_1 + g_{12}EX_2)(g_{21}EX_1 + g_{22}EX_2) \\ &= g_{11}g_{21}(EX_1)^2 + g_{12}g_{22}(\mathbf{s}_{X_2}^2 + (EX_2)^2) + (g_{11}g_{22} + g_{12}g_{21})(EX_1EX_2) \\ \text{cov}(Y_1, Y_2) &= EY_1Y_2 - EY_1EY_2 \\ &= g_{11}g_{21}(\mathbf{s}_{X_1}^2) + g_{12}g_{22}(\mathbf{s}_{X_2}^2) + (g_{11}g_{22} + g_{12}g_{21})\text{cov}(X_1, X_2)\end{aligned}$$