

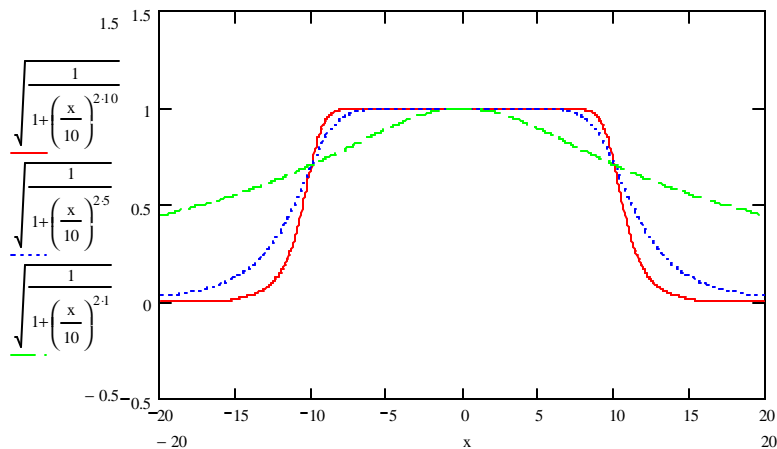
Continuous-time low-pass filter

Butterworth filter

- N^{th} -order Butterworth filter with cutoff frequency Ω_c :

$$\left| \hat{H}_c(\Omega) \right|^2 = \frac{1}{1 + \left(\frac{\Omega}{\Omega_c} \right)^{2N}}$$

- Very flat @ 0 : $(N-1)$ derivative = 0 @ 0



- Magnitude is monotonically decreasing in $|\Omega|$
- Passband error is worse near Ω_c

- $\left| \hat{H}_c(\Omega_c) \right| = \frac{1}{\sqrt{1 + \left(\frac{\Omega_c}{\Omega_c} \right)^{2N}}} = \frac{1}{\sqrt{2}} = 0.707$

- $H_c(s) = \frac{\Omega_c^N}{\prod_{i=1}^N (s - s_i)}$

- s_i : poles of $H_c(s)$

- Odd N: $\Omega_c \times \left(e^{j\frac{m\pi}{N}} \text{ that are in } \text{Re}\{s\} < 0 \right); 0 \leq m < 2N$

- Even N: $\Omega_c \times \left(e^{j\left(\frac{p}{2N} + m\frac{\pi}{N}\right)} \text{ that are in } \text{Re}\{s\} < 0 \right); 0 \leq m < 2N$

- ROC: region to the right of all poles

Fact: $\left| \hat{H}_c(\Omega) \right|^2 = H_c(-s)H_c(s) \Big|_{s=j\Omega}$

- $$H_c(s) = \frac{\Omega_c^N}{\prod_{i=1}^N (s - s_i)}$$

$$H_c(-s)H_c(s) = \left(\frac{\Omega_c^N}{\prod_{i=1}^N (-s - s_i)} \right) \left(\frac{\Omega_c^N}{\prod_{i=1}^N (s - s_i)} \right) = \frac{\Omega_c^{2N}}{\left(\prod_{i=1}^N (-s - s_i) \right) \left(\prod_{i=1}^N (s - s_i) \right)}$$

From this equation, $H_c(-s)H_c(s)$ has 2N pole N s_i 's and N $-s_i$'s

Want $H_c(s)$ to be stable

⇒ have poles in $\text{Re}\{s_i\} < 0$

⇒ the left-half-plane poles is for $H_c(s)$;

(the right-half-plane poles is for $H_c(-s)$)

- From $|\hat{H}_c(\Omega)|^2 = H_c(-s)H_c(s)|_{s=j\Omega} \Rightarrow H_c(-s)H_c(s) = |\hat{H}_c(\Omega)|^2 \Big|_{\Omega=\frac{s}{j}}$

$$\begin{aligned} H_c(-s)H_c(s) &= \left| \hat{H}_c(\Omega) \right|^2 \Big|_{\Omega=\frac{s}{j}} = \frac{1}{1 + \left(\frac{s}{j\Omega_c} \right)^{2N}} = \frac{1}{1 + \frac{s^{2N}}{j^{2N}\Omega_c^{2N}}} \\ &= \frac{1}{1 + \frac{s^{2N}}{(-1)^N \Omega_c^{2N}}} = \frac{\Omega_c^{2N}}{\Omega_c^{2N} + (-1)^N s^{2N}} \end{aligned}$$

From this equation, $H_c(-s)H_c(s)$ has 2N pole at

$$\Omega_c^{2N} + (-1)^N s_i^{2N} = 0 \Rightarrow s_i^{2N} = -(-1)^N \Omega_c^{2N}$$

- If N is odd, poles: $s_i^{2N} = \Omega_c^{2N}$

$$s_i = \Omega_c \times \left((2N)^{\text{th}} \text{-roots of unity} \right) = \Omega_c \times e^{jm\frac{2\pi}{2N}}; 0 \leq m < 2N$$

- If N is even, poles: $s_i^{2N} = -\Omega_c^{2N} = e^{j\pi} \Omega_c^{2N}$

$$s_i = e^{j\left(\frac{\pi}{2N} + m\frac{2\pi}{2N}\right)} \Omega_c$$

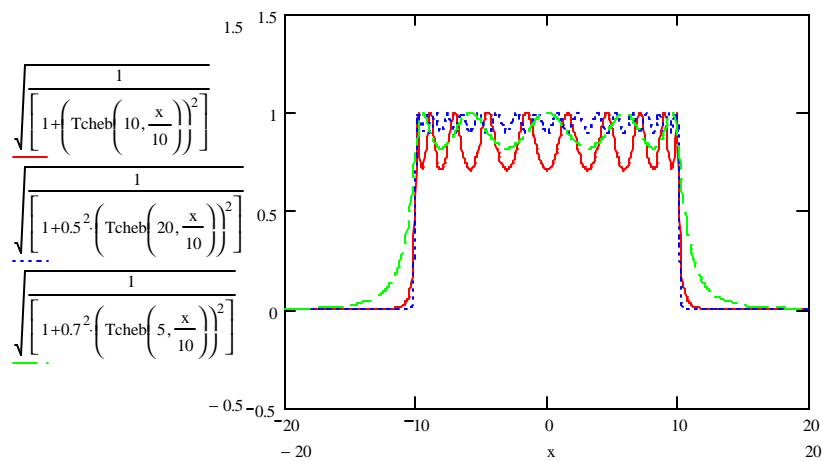
Chebyshev filter

Type I

- Nth-order Chebyshev filter with cutoff Ω_c type I

$$\left| \hat{H}_c(\Omega) \right|^2 = \frac{1}{1 + e^2 V_N^2 \left(\frac{\Omega}{\Omega_c} \right)}$$

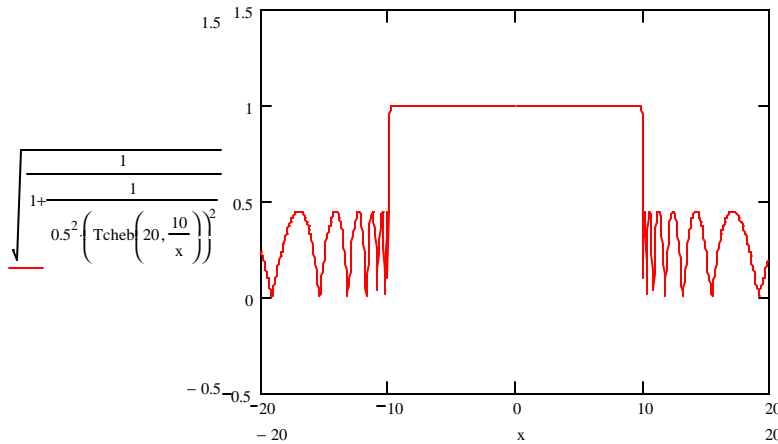
- $V_N(x)$ = the N^{th} Chebyshev polynomial in x
- $V_{N+1}(x) = 2xV_N(x) - V_{N-1}(x)$
- $\left| \hat{H}_c(\Omega_c) \right|^2 = \frac{1}{1 + e^2 V_N^2 \left(\frac{\Omega_c}{\Omega_c} \right)} = \frac{1}{1 + e^2} \approx 1$
- Equiripple in passband \Rightarrow error is distributed uniformly
 - To achieve a given passband max. error, require lower-order (N) than butterworth
- Monotonic in stopband



Type II

- N^{th} -order Chebyshev filter with cutoff Ω_c type II

$$\left| \hat{H}_c(\Omega) \right|^2 = \frac{1}{1 + \frac{1}{e^2 V_N^2 \left(\frac{\Omega_c}{\Omega} \right)}}$$



- Monotonic in passband
- Equiripple in stopband

Elliptic filter

- N^{th} -order Elliptic filter with cutoff Ω_c :

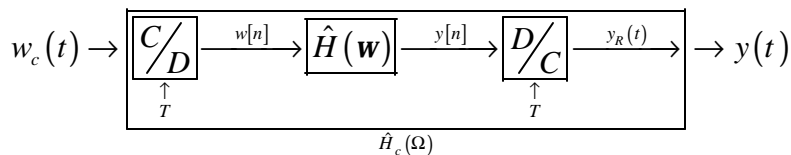
$$\left| \hat{H}_c(\Omega) \right|^2 = \frac{1}{1 + e^2 U_N^2\left(\frac{\Omega}{\Omega_c}\right)}$$

- $U_N(x) = N^{\text{th}}$ Jacobian elliptic function of x
- Equiripple both in passband and stopband
- Require smaller N than Chebyshev to achieve max error in passband or stopband

Digital filter design

Old-fashioned DSP paradigm

- Processing continuous-time signals with the aid of discrete-time systems



Objective: Given $\hat{H}_{desired}(\Omega) = \hat{H}_c(\Omega)$, find T and $\hat{H}(\mathbf{w})$ so that $\hat{Y}(\Omega) \approx \hat{H}_c(\Omega)\hat{W}_c(\Omega)$

Restrict to band-limited input $w_c(t)$ and $T < \frac{P}{\Omega_m}$

Solution: use $\hat{H}(\mathbf{w}) = \hat{H}_c\left(\frac{\mathbf{w}}{T}\right)$, $|\mathbf{w}| \leq P$

- Note: here, we are not sampling $h_c(t)$ to get $h[n]$. So, can't find the relationship using the deconstruction. $h[n]$ is some signal that, when used, will make the whole discrete system $\left(\boxed{C/D}, \boxed{\hat{H}(\mathbf{w})}, \boxed{D/C} \right)$ act like $\hat{H}_c(\Omega)$.

Proof

- $\hat{W}(\Omega T) = \frac{1}{T} \hat{W}_c(\Omega)$ for $|\Omega| \leq \frac{P}{T}$, assuming no aliasing

$$\hat{W}(\mathbf{w}) = \sum_{k=-\infty}^{\infty} \left(\frac{1}{T} \hat{W}_c \left(\frac{\mathbf{w}}{T} + k \frac{2P}{T} \right) \right)$$

$$\text{If no aliasing, } \hat{W}(\mathbf{w}) = \frac{1}{T} \hat{W}_c \left(\frac{\mathbf{w}}{T} \right) ; \text{ for } -P \leq \mathbf{w} \leq P$$

$$\text{or } \hat{W}(\mathbf{w}) p_p(\mathbf{w}) = \frac{1}{T} \hat{W}_c \left(\frac{\mathbf{w}}{T} \right)$$

- $\hat{W}(\Omega T) = \sum_{k=-\infty}^{\infty} \frac{1}{T} \hat{W}_c \left(\Omega + k \frac{2P}{T} \right)$
 $= \frac{1}{T} \hat{W}_c(\Omega)$ for $|\Omega| \leq \frac{P}{T}$, assuming no aliasing

- $\hat{Y}_R(\Omega) = \hat{H}(\Omega T) \hat{W}_c(\Omega)$, $\forall \mathbf{w}$

$$\text{From } \hat{Y}(\mathbf{w}) = \hat{H}(\mathbf{w}) \hat{W}(\mathbf{w}), \text{ and } \hat{Y}_R(\Omega) = T \left(\hat{Y}(\mathbf{w}) p_p(\mathbf{w}) \right) \Big|_{\mathbf{w}=\Omega T},$$

$$\hat{Y}_R(\Omega) = T \left(\hat{H}(\mathbf{w}) \hat{W}(\mathbf{w}) p_p(\mathbf{w}) \right) \Big|_{\mathbf{w}=\Omega T}.$$

$$\text{Substitute } \hat{W}(\mathbf{w}) p_p(\mathbf{w}) = \frac{1}{T} \hat{W}_c \left(\frac{\mathbf{w}}{T} \right):$$

$$\hat{Y}_R(\Omega) = T \left(\hat{H}(\mathbf{w}) \frac{1}{T} \hat{W}_c \left(\frac{\mathbf{w}}{T} \right) \right) \Big|_{\mathbf{w}=\Omega T} = \hat{H}(\Omega T) \hat{W}_c(\Omega)$$

- Thus, want $\hat{H}(\mathbf{w}) = \hat{H}_c \left(\frac{\mathbf{w}}{T} \right)$, $|\mathbf{w}| \leq P$, or

$$\hat{H}(\Omega T) = \hat{H}_c(\Omega) \text{ at least for } |\Omega| \leq \frac{P}{T}.$$

Don't need to worry about $|\Omega| > \frac{P}{T}$ since $\hat{W}_c(\Omega) = 0$ there.

New-fashioned DSP paradigm

- Given $\hat{H}_{\text{des}}(\omega)$.

Design an implementable discrete-time system with $\hat{H}(\omega) \approx \hat{H}_{\text{des}}(\omega)$

IIR filter design

- IIR \Rightarrow infinite-duration impulse response
- Always assume $h[n]$ is real-valued

IIR filter design using impulse invariance

- Design a discrete-time low-pass filter $\hat{H}_{des}(\mathbf{w})$
(from available $\hat{H}_c(\Omega)$)
with cutoff \mathbf{w}_c
need to meet design specs
- Pick $T_d > 0$; $d =$ design
- Via $\mathbf{w} = \mathbf{W}\mathbf{T}_d$, translate $\hat{H}_{des}(\mathbf{w}) \rightarrow \hat{H}_{c,des}(\Omega)$; $\left(\Omega_c = \frac{\mathbf{w}_c}{T_d}\right)$ along with design specs
- Design $h_c(t)$ that meets the continuous-time design specs and
 - **stable & causal**
 - rational $H_c(s)$
- Set $h[n] = T_d h_c(nT_d)$. See whether this work.

- $\hat{H}(\mathbf{w}) = T_d \sum_{k=-\infty}^{\infty} \frac{1}{T_d} \hat{H}_c\left(\frac{\mathbf{w}}{T_d} + k \frac{2\mathbf{p}}{T_d}\right) = \sum_{k=-\infty}^{\infty} \hat{H}_c\left(\frac{\mathbf{w}}{T_d} + k \frac{2\mathbf{p}}{T_d}\right)$
- $T_d > 0$ doesn't matter
- $\frac{\mathbf{p}}{T_d} > \Omega_c = \frac{\mathbf{w}_c}{T_d} \Rightarrow$ small aliasing if $\hat{H}_c(\Omega) \approx 0$ outside some bound (Ω_c)
- Aliasing might cause $\hat{H}(\mathbf{w})$ not to meet original design specs (especially if $\hat{H}_c(\Omega)$ barely does the job in continuous time) \Rightarrow If this occurs, then should over-design

$$\bullet \left\{ \begin{array}{l} h_c(t) = \sum_{\ell} k_{\ell} e^{s_{\ell} t} u(t) \\ H_c(s) = \sum_{\ell} \frac{k_{\ell}}{s - s_{\ell}} ; \text{Re}\{s\} > \max_{\ell} \text{Re}\{s_{\ell}\} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} h[n] = T_d \sum_{\ell} k_{\ell} (z_{\ell})^n u[n] ; z_{\ell} = e^{s_{\ell} T_d} \\ H(z) = T_d \sum_{\ell} \frac{k_{\ell} z}{z - z_{\ell}} ; |z| > \max |z_{\ell}| \end{array} \right\}$$

- $h_c(t)$ is stable, causal, and has rational $H_c(s) \Rightarrow$
 $h[n]$ is stable, causal, and has rational $H(z)$
- $h_c(t)$ is not band-limited \Rightarrow there is aliasing when convert to $h[n]$
- pole $H_c(s)$ @ $s_0 \Rightarrow$ pole $H(z)$ @ $e^{s_0 T_d}$
- $h_c(t) = \sum_{\ell} k_{\ell} e^{s_{\ell} t} u(t) \xLeftrightarrow{\mathcal{L}} H_c(s) = \sum_{\ell} \frac{k_{\ell}}{s - s_{\ell}} ; \text{Re}\{s\} > \max_{\ell} \text{Re}\{s_{\ell}\}$
 - $s_{\ell} =$ poles of $H_c(s)$

- Stable iff all poles of rational $H(s)$ lies in $\text{Re}\{s\} < 0$. So need $\text{Re}\{s_\ell\} < 0, \forall \ell$
- $h[n] = T_d h_c(nT_d) = T_d \sum_{\ell} k_{\ell} e^{s_{\ell} n T_d} u[n] = T_d \sum_{\ell} k_{\ell} (e^{s_{\ell} T_d})^n u[n] = T_d \sum_{\ell} k_{\ell} (z_{\ell})^n u[n]$
- $z_{\ell} = \text{poles of } H(z) = e^{s_{\ell} T_d}$
- $h[n] = T_d \sum_{\ell} k_{\ell} (z_{\ell})^n u[n] \xleftrightarrow{z} H(z) = T_d \sum_{\ell} \frac{k_{\ell} z}{z - z_{\ell}} = T_d \sum_{\ell} \frac{k_{\ell} z}{z - e^{s_{\ell} T_d}}$;
 $|z| > \max |z_{\ell}| = \max |e^{s_{\ell} T_d}|$
- $\text{Re}\{s_{\ell}\} < 0 \Rightarrow |z_{\ell}| = |e^{s_{\ell} T_d}| < 1 \Rightarrow \text{stable}$
- Reverse process is not uniquely determined

IIR filter design using bilinear transformation

- Want a discrete-time low-pass filter $\hat{H}_{des}(\mathbf{w})$ with cutoff ω_c
need to meet design specs
 - Pick any $T_d > 0$
 - Via $\Omega = \frac{2}{T_d} \tan\left(\frac{\mathbf{w}}{2}\right)$, translate $\hat{H}_{des}(\mathbf{w}) \rightarrow \hat{H}_{c,des}(\Omega)$ (equal height); along with design specs
 - Design $h_c(t) / H_c(s)$ that meets the continuous-time design specs and
 - stable & causal
 - rational $H_c(s)$
 - $H(z) = H_c\left(s = \frac{2}{T_d} \frac{1 - z^{-1}}{1 + z^{-1}}\right)$
- See whether $\hat{H}(\mathbf{w}) = H(z = e^{j\mathbf{w}})$ work.

- Idea

Trapezoidal approximation

$$y(t) = \int w(\mathbf{t}) dt \Rightarrow y(nT_d) - y((n-1)T_d) \approx \frac{T_d}{2} (w(nT_d) + w((n-1)T_d))$$

$$y[n] - y[n-1] \approx \frac{T_d}{2} (w[n] + w[n-1])$$

$$(1 - z^{-1})Y(z) \approx \frac{T_d}{2} (1 + z^{-1})W(z)$$

$$H(z) = \frac{Y(z)}{W(z)} \approx \frac{T_d}{2} \frac{1 + z^{-1}}{1 - z^{-1}}$$

Imaginary axis in s-space ($s = j\Omega$)

maps onto

unit circle in z -space ($z = e^{j\omega}$)

$$\Rightarrow j\Omega = \frac{2}{T_d} \frac{1 - e^{-j\omega}}{1 + e^{-j\omega}} \Rightarrow$$

$$\Omega = \frac{2}{jT_d} \frac{1 - e^{-j\omega}}{1 + e^{-j\omega}} = \frac{2}{jT_d} \frac{e^{-j\frac{\omega}{2}} \frac{1 - e^{-j\frac{\omega}{2}}}{e^{-j\frac{\omega}{2}}}}{e^{-j\frac{\omega}{2}} \frac{1 + e^{-j\frac{\omega}{2}}}{e^{-j\frac{\omega}{2}}}} = \frac{2}{T_d} \frac{j \sin\left(\frac{\omega}{2}\right)}{\cos\left(\frac{\omega}{2}\right)} = \frac{2}{T_d} \tan\left(\frac{\omega}{2}\right)$$

- Note: Continuous-time integrator $\Rightarrow H_I(s) = \frac{1}{s}$
- All of Ω -space, ie, $-\infty < \Omega < \infty$
maps onto
 $-\pi \leq \omega \leq \pi$ in ω -space (and 2π -periodic)
- No aliasing
- Non-linear mapping between ω and Ω
 - Not a big problem if $\hat{H}_{c,des}(\Omega) \approx$ piecewise-constant
- $\hat{H}_{c,des}(\Omega)$'s phase characteristics get dangerously twisted

- s_0 is a pole of $H_c(s) \Rightarrow z_0 = \frac{\frac{2}{T_d} + s_0}{\frac{2}{T_d} - s_0}$ is a pole of $H(z)$
- If $\text{Re}\{s_0\} < 0$, then $|z_0| < 1$
- $H(z)$ is rational and stable, if $H_c(s)$ is rational, causal, and stable

$$\bullet \text{ Let } H(z) = H_c\left(s = \mathbf{b} \frac{1 - z^{-M}}{1 + z^{-M}}\right),$$

$H_c(s)$ is rational & stable ($\text{Re}\{s_0\} < 0$), \mathbf{b} is real, and M is a non-zero integer.

Then

- $H(z)$ is rational
- $H(z)$ is stable ($|z_0| < 1$) if \mathbf{b} and M have same sign

Proof

$$s_0 = \mathbf{b} \frac{1 - z_0^{-M}}{1 + z_0^{-M}} \Rightarrow s_0 + s_0 z_0^{-M} = \mathbf{b} - \mathbf{b} z_0^{-M} \Rightarrow z_0^{-M} = \frac{\mathbf{b} - s_0}{\mathbf{b} + s_0}$$

$$|z_0^M| = |z_0|^M = \left| \frac{\mathbf{b} + s_0}{\mathbf{b} - s_0} \right| = \left| \frac{\mathbf{b} + \text{Re}\{s_0\} + j \text{Im}\{s_0\}}{\mathbf{b} - \text{Re}\{s_0\} - j \text{Im}\{s_0\}} \right|$$

$$= \sqrt{\frac{(\mathbf{b} + \text{Re}\{s_0\})^2 + (\text{Im}\{s_0\})^2}{(\mathbf{b} - \text{Re}\{s_0\})^2 + (\text{Im}\{s_0\})^2}}$$

- For $M > 0$; want $|z_0| < 1 \Rightarrow |z_0|^M < 1$

$$(\mathbf{b} + \text{Re}\{s_0\})^2 + \cancel{(\text{Im}\{s_0\})^2} < (\mathbf{b} - \text{Re}\{s_0\})^2 + \cancel{(\text{Im}\{s_0\})^2}$$

$$\cancel{\mathbf{b}^2} + \cancel{2\mathbf{b} \text{Re}\{s_0\}} + \cancel{\text{Re}^2\{s_0\}} < \cancel{\mathbf{b}^2} - \cancel{2\mathbf{b} \text{Re}\{s_0\}} + \cancel{\text{Re}^2\{s_0\}}$$

$$\mathbf{b} \text{Re}\{s_0\} < -\mathbf{b} \text{Re}\{s_0\}$$

$$2\mathbf{b} \text{Re}\{s_0\} < 0$$

$$\mathbf{b} > 0; \text{Re}\{s_0\} < 0$$

- For $M < 0$; want $|z_0| < 1 \Rightarrow |z_0|^M > 1$

$$(\mathbf{b} + \text{Re}\{s_0\})^2 + \cancel{(\text{Im}\{s_0\})^2} > (\mathbf{b} - \text{Re}\{s_0\})^2 + \cancel{(\text{Im}\{s_0\})^2}$$

$$\cancel{\mathbf{b}^2} + \cancel{2\mathbf{b} \text{Re}\{s_0\}} + \cancel{\text{Re}^2\{s_0\}} > \cancel{\mathbf{b}^2} - \cancel{2\mathbf{b} \text{Re}\{s_0\}} + \cancel{\text{Re}^2\{s_0\}}$$

$$\mathbf{b} \text{Re}\{s_0\} > -\mathbf{b} \text{Re}\{s_0\}$$

$$2\mathbf{b} \text{Re}\{s_0\} > 0$$

$$\mathbf{b} < 0; \text{Re}\{s_0\} < 0$$

Equalization

- Design $\hat{H}(\mathbf{w})$ to undo effect of $\hat{G}(\mathbf{w})$

- Can set $H(z) = \frac{1}{G(z)}$

- Ex. work if $G(z) = \frac{z^{a \geq d}}{\text{polynomial}(z) \text{ degree} = d}$

$$H(z) = k_0 + k_1 z^{-1} + \dots \text{ and } h[n] = k_0 \delta[n] + k_1 \delta[n-1] + \dots$$

- Not always get causal/stable answer

- Ex. $G(z) = \frac{z^{a < d}}{\text{polynomial}(z) \text{ degree} = d}$

Get z^+ in $H(z)$ and $h[n]$ is not causal

solution: design so that $H(z)G(z) = z^{a-d}$ and then the result is simply a delay

Phase

- In general, we have $\hat{H}(\mathbf{w}) = |\hat{H}(\mathbf{w})|e^{-j\mathbf{f}(\mathbf{w})}$
 - $\mathbf{f}(\mathbf{w})$ is 2π -periodic,
not uniquely determined due to 2π -multiple ambiguity
- Causal real-valued $h[n]$ cannot have zero phase $\hat{H}(\mathbf{w}) = |\hat{H}(\mathbf{w})|$ nor constant phase $\hat{H}(\mathbf{w}) = |\hat{H}(\mathbf{w})|e^{-j\mathbf{b}}$ unless $h[n] = K_0\mathbf{d}[n]$
 - $h[n]$ real $\Rightarrow \hat{H}(-\mathbf{w}) = \hat{H}^*(\mathbf{w})$
- Case when $\hat{H}(\mathbf{w}) = |\hat{H}(\mathbf{w})|e^{-j\mathbf{a}\mathbf{w}}$; $\mathbf{a} = \mathbf{n}_0$, a (positive) integer

- If $w[n] \rightarrow \boxed{|\hat{H}_{des}(\mathbf{w})|} \rightarrow y_{des}[n]$, then

$$w[n] \rightarrow \boxed{\hat{H}(\mathbf{w}) = |\hat{H}_{des}(\mathbf{w})|e^{-j\mathbf{n}_0\mathbf{w}}} \rightarrow y_{des}[n - n_0]$$

\Rightarrow simple time-delay

Proof

$$\hat{Y}_{des}(\mathbf{w}) = \hat{W}(\mathbf{w})|\hat{H}_{des}(\mathbf{w})|$$

$$\hat{Y}'(\mathbf{w}) = \hat{W}(\mathbf{w})|\hat{H}_{des}(\mathbf{w})|e^{-j\mathbf{n}_0\mathbf{w}} = \hat{Y}_{des}(\mathbf{w})e^{-j\mathbf{n}_0\mathbf{w}} \xrightarrow{DTFT^{-1}} y_{des}[n - n_0]$$

by time-shift rule.

- $h[n] = h_{des}[n - n_0]$

$$h_{des}[n] \xleftrightarrow{DTFT} \hat{H}_{des}(\mathbf{w}) = |\hat{H}_{des}(\mathbf{w})|$$

$$h[n] \xrightarrow{DTFT} |\hat{H}_{des}(\mathbf{w})|e^{-j\mathbf{n}_0\mathbf{w}} \xrightarrow{DTFT^{-1}} h_{des}[n - n_0]$$
 - If $h_{des}[n]$ is FIR, then $h[n] = h_{des}[n - n_0]$ will be causal for n_0 large enough

- $e^{jn_0\mathbf{w}} \rightarrow \boxed{e^{-j\mathbf{n}_0\mathbf{w}}} \rightarrow e^{-j\mathbf{n}_0\mathbf{w}_0} e^{jn_0\mathbf{w}_0} = e^{j(n-n_0)\mathbf{w}_0}$

- Case when $\hat{H}(\mathbf{w}) = |\hat{H}(\mathbf{w})|e^{-j\mathbf{a}\mathbf{w}}$; **real a**

- $\hat{H}(\mathbf{w}) = e^{-j\mathbf{a}\mathbf{w}} \xrightarrow{DTFT^{-1}} h[n] = \frac{1}{2\mathbf{p}} \int_{-\mathbf{p}}^{\mathbf{p}} e^{-j\mathbf{a}\mathbf{w}} e^{j\mathbf{n}\mathbf{w}} d\mathbf{w} = \frac{\sin(\mathbf{p}(n - \mathbf{a}))}{\mathbf{p}(n - \mathbf{a})}$

- for integer $\mathbf{a} = n_0$, $h[n] = \mathbf{d}[n - n_0]$

- $w[n] \rightarrow \boxed{\frac{D}{C}} \xrightarrow{w_c(t)} \boxed{e^{-j\mathbf{a}T\Omega}} \xrightarrow{y_c(t) = w_c(+\mathbf{a}T)} \boxed{\frac{C}{D}} \rightarrow y[n] = y_c(nT)$

Proof

$$\hat{W}_c(\Omega) = \hat{W}_R(\Omega) = \begin{cases} T\hat{W}(\Omega T) & -\frac{P}{T} \leq \Omega \leq \frac{P}{T} \\ 0 & |\Omega| > \frac{P}{T} \end{cases}$$

$$\hat{Y}_c(\Omega) = \hat{W}_c(\Omega)e^{-jaT\Omega} = \begin{cases} Te^{-ja\Omega T}\hat{W}(\Omega T) & -\frac{P}{T} \leq \Omega \leq \frac{P}{T} \\ 0 & |\Omega| > \frac{P}{T} \end{cases}$$

$$\hat{Y}(\mathbf{w}) = \sum_{k=-\infty}^{\infty} \frac{1}{T} \hat{Y}_c\left(\frac{\mathbf{w}}{T_d} + k\frac{2P}{T}\right) = e^{-ja\mathbf{w}} \hat{W}(\mathbf{w}) ; |\mathbf{w}| \leq P$$

- $e^{jn\mathbf{w}_0} \rightarrow \boxed{e^{-ja\mathbf{w}_0}} \rightarrow (e^{-ja\mathbf{w}_0}) e^{jn\mathbf{w}_0} = e^{j(n-a)\mathbf{w}_0}$
- $e^{jn\mathbf{w}_0} \rightarrow \boxed{\frac{D}{C}} \xrightarrow{e^{j\frac{T}{T}\mathbf{w}_0}} \boxed{e^{-jaT\mathbf{w}_0}} \xrightarrow{e^{j\frac{-aT}{T}\mathbf{w}_0}} \boxed{\frac{C}{D}} \rightarrow e^{j\frac{nT-aT}{T}\mathbf{w}_0} = e^{j(n-a)\mathbf{w}_0}$

- **Generalized linear phase:** $\hat{H}(\mathbf{w}) = A(\mathbf{w})e^{-j(\mathbf{a}\mathbf{w}+b)}$
 - Real \mathbf{a} , \mathbf{b} , $A(\mathbf{w})$
 - Can be expressed with $\mathbf{b} = 0$ or $\frac{P}{2}$ for real $h[n]$

Proof

$$h[n] \text{ is real} \Rightarrow \hat{H}(-\mathbf{w}) = \hat{H}^*(\mathbf{w})$$

$$A(-\mathbf{w})e^{-j(-\mathbf{a}\mathbf{w}+b)} = A(\mathbf{w})e^{j(\mathbf{a}\mathbf{w}+b)}$$

$$A(-\mathbf{w}) = A(\mathbf{w})e^{j2b} \quad \text{real}$$

So e^{j2b} is real = trivial 0, 1, or -1

- If $e^{j2b} = 1$, $e^{jb} = \pm 1 \Rightarrow$ absorb e^{jb} into $A(\mathbf{w})$ and $\mathbf{b} = 0$
- If $e^{j2b} = -1$, $e^{jb} = \pm j \Rightarrow$ absorb sign into $A(\mathbf{w})$ and $e^{jb} = j \Rightarrow \mathbf{b} = \frac{P}{2}$
- **Truly linear phase** when $\mathbf{b} = 0$ and $A(\mathbf{w}) \geq 0 \forall \mathbf{w}$
 - Let $A(\mathbf{w}) = |\hat{H}(\mathbf{w})|$, then $\hat{H}(\mathbf{w}) = |\hat{H}(\mathbf{w})|e^{-ja\mathbf{w}}$

FIR filter design

FIR filter with generalized linear phase (g.l.p.)

- Every generalized-linear-phase FIR filter $\hat{H}(\mathbf{w}) = A(\mathbf{w})e^{-j(\mathbf{a}\mathbf{w}+b)}$ is of one of these 4 types:

Type	I	II	III	IV
$h[M+m]=$ M = midpoint	$h_I[M-m]$	$h_{II}[M+1-m]$	$-h_{III}[M-m]$	$-h_{IV}[M+1-m]$
h[n] duration = N	odd	even	odd	even
Midpoint @	M	M, M+1	M	M, M+1
h[n] around midpoint	even	even	odd	odd
#unknown h[n] = η	$\frac{N+1}{2}$	$\frac{N}{2}$	$\frac{N-1}{2}$	$\frac{N}{2}$
A(ω) about 0	even	even	odd	odd
A(ω) @ 0	$\neq 0$	$\neq 0$	0	0
A(ω) about π	even	odd	odd	even
A(ω) @ π	$\neq 0$	0	0	$\neq 0$
α	M	$M+\frac{1}{2}$	M	$M+\frac{1}{2}$
β	0	0	$\frac{p}{2}$	$\frac{p}{2}$
Think about A(ω) as	$\cos(\omega)$	$\cos\left(\frac{\omega}{2}\right)$	$\sin(\omega)$	$\sin\left(\frac{\omega}{2}\right)$
filter	H,L	L		H
After shifted by π in ω or $\times(-1)^n$ in n	I	IV	I	II

- $A_I(\omega) = h[M] + \sum_{m>0} \{2h[M+m]\cos(m\omega)\}$
- $A_{II}(\omega) = \sum_{m>0} \left\{ 2h[M+m]\cos\left(\left(m-\frac{1}{2}\right)\omega\right) \right\}$
- $A_{III}(\omega) = \sum_{m>0} \{2h[M+m]\sin(m\omega)\}$
- $A_{IV}(\omega) = \sum_{m>0} \left\{ 2h[M+m]\sin\left(\left(m-\frac{1}{2}\right)\omega\right) \right\}$

- Type I
 - $h_I[n]$
 - Odd duration N
 - Even-symmetric about midpoint $h[M]$: $h_I[M+m] = h_I[M-m], \forall m > 0$
- $\mathbf{a} = M, \mathbf{b} = 0$

- $A_I(\mathbf{w}) = h[M] + \sum_{m>0} \{2h[M+m]\cos(m\mathbf{w})\}$

Proof

$$\begin{aligned}\hat{H}_I(\mathbf{w}) &= \sum_n h[n]e^{-jn\mathbf{w}} \\ &= h[M]e^{-jM\mathbf{w}} + \sum_{m>0} \{h[M+m]e^{-j(M+m)\mathbf{w}} + h[M-m]e^{-j(M-m)\mathbf{w}}\} \\ &= h[M]e^{-jM\mathbf{w}} + e^{-jM\mathbf{w}} \sum_{m>0} \{h[M+m]e^{-jm\mathbf{w}} + h[M-m]e^{+jm\mathbf{w}}\} \\ &= \left[h[M] + \sum_{m>0} \{2h[M+m]\cos(m\mathbf{w})\} \right] e^{-jM\mathbf{w}}\end{aligned}$$

- Even about $\mathbf{w} = 0$: $A(0+\mathbf{w}) = A(0-\mathbf{w})$

Proof $\cos(m(-\mathbf{w})) = \cos(m\mathbf{w})$

- Even about $\mathbf{w} = \pi$: $A(\mathbf{p}+\mathbf{w}) = A(\mathbf{p}-\mathbf{w})$

Proof

$$\begin{aligned}\cos(m(\mathbf{p}+\mathbf{w})) &= \frac{1}{2} \left(e^{j(mp+m\mathbf{w})} + e^{-j(mp+m\mathbf{w})} \right) \\ &= \frac{1}{2} \left(e^{jmp} e^{jm\mathbf{w}} + e^{-jmp} e^{-jm\mathbf{w}} \right) = (-1)^m \cos(m\mathbf{w}) \\ \cos(m(\mathbf{p}-\mathbf{w})) &= \frac{1}{2} \left(e^{j(mp-m\mathbf{w})} + e^{-j(mp-m\mathbf{w})} \right) \\ &= \frac{1}{2} \left(e^{jmp} e^{-jm\mathbf{w}} + e^{-jmp} e^{+jm\mathbf{w}} \right) = (-1)^m \cos(m\mathbf{w})\end{aligned}$$

- Periodic with period 2π : $A(\mathbf{w}+2\mathbf{p}) = A(\mathbf{w})$

Proof $\cos(m(\mathbf{w}+2\mathbf{p})) = \cos(m\mathbf{w}+m2\mathbf{p}) = \cos(m\mathbf{w})$

- Type II

- $h[n]$

- Even duration N

- Even-symmetric about midpoint $h[M] = h[M+1]$:

$$h_n[M+m] = h_n[M+1-m], \forall m > 0$$

- $\mathbf{a} = M + \frac{1}{2}$, $\mathbf{b} = 0$

- $A_{II}(\mathbf{w}) = \sum_{m>0} \left\{ 2h[M+m]\cos\left(\left(m - \frac{1}{2}\right)\mathbf{w}\right) \right\}$

Proof

$$\begin{aligned}
\hat{H}_H(\mathbf{w}) &= \sum_n h[n] e^{-jn\mathbf{w}} \\
&= \sum_{m>0} \left\{ h[M+m] e^{-j(M+m)\mathbf{w}} + h[M+1-m] e^{-j(M+1-m)\mathbf{w}} \right\} \\
&= e^{-j\left(M+\frac{1}{2}\right)\mathbf{w}} \sum_{m>0} \left\{ h[M+m] e^{-j\left(m-\frac{1}{2}\right)\mathbf{w}} + h[M+m] e^{+j\left(m-\frac{1}{2}\right)\mathbf{w}} \right\} \\
&= \left[\sum_{m>0} \left\{ 2h[M+m] \cos\left(\left(m-\frac{1}{2}\right)\mathbf{w}\right) \right\} \right] e^{-j\left(M+\frac{1}{2}\right)\mathbf{w}}
\end{aligned}$$

- Even about $\mathbf{w} = 0$: $A(0 + \mathbf{w}) = A(0 - \mathbf{w})$

$$\text{Proof } \cos\left(\left(m-\frac{1}{2}\right)(-\mathbf{w})\right) = \cos\left(\left(m-\frac{1}{2}\right)\mathbf{w}\right)$$

- Odd about $\mathbf{w} = \pi$: $A(\mathbf{p} + \mathbf{w}) = -A(\mathbf{p} - \mathbf{w})$

Proof

$$\begin{aligned}
\cos\left(\left(m-\frac{1}{2}\right)(\mathbf{p} + \mathbf{w})\right) &= \cos\left(m\mathbf{p} - \frac{\mathbf{p}}{2} + m\mathbf{w} - \frac{\mathbf{w}}{2}\right) \\
&= \text{Re} \left\{ e^{jm\mathbf{p}} e^{-j\frac{\mathbf{p}}{2}} e^{jm\mathbf{w}} e^{-j\frac{\mathbf{w}}{2}} \right\} \\
&= \text{Re} \left\{ (-1)^m (-j) e^{jm\mathbf{w}} e^{-j\frac{\mathbf{w}}{2}} \right\} \\
&= (-1)^m \sin\left(m\mathbf{w} - \frac{\mathbf{w}}{2}\right)
\end{aligned}$$

$$\begin{aligned}
\cos\left(\left(m-\frac{1}{2}\right)(\mathbf{p} - \mathbf{w})\right) &= \cos\left(m\mathbf{p} - \frac{\mathbf{p}}{2} - m\mathbf{w} + \frac{\mathbf{w}}{2}\right) \\
&= \text{Re} \left\{ e^{jm\mathbf{p}} e^{-j\frac{\mathbf{p}}{2}} e^{-jm\mathbf{w}} e^{+j\frac{\mathbf{w}}{2}} \right\} \\
&= \text{Re} \left\{ (-1)^m (-j) e^{-jm\mathbf{w}} e^{+j\frac{\mathbf{w}}{2}} \right\} \\
&= (-1)^m \sin\left(-m\mathbf{w} + \frac{\mathbf{w}}{2}\right) \\
&= -(-1)^m \sin\left(m\mathbf{w} - \frac{\mathbf{w}}{2}\right)
\end{aligned}$$

- Periodic with period 4π : $A(\mathbf{w} + 4\mathbf{p}) = A(\mathbf{w})$

$$\begin{aligned} \text{Proof } \cos\left(\left(m - \frac{1}{2}\right)(\mathbf{w} + 4\mathbf{p})\right) &= \cos\left(\left(m - \frac{1}{2}\right)\mathbf{w} + 4m\mathbf{p} - 2\mathbf{p}\right) \\ &= \cos\left(\left(m - \frac{1}{2}\right)\mathbf{w}\right) \end{aligned}$$

- Type III
 - $h[n]$
 - Odd duration N
 - $h[M] = 0$
 - Odd-symmetric about midpoint $h[M] = 0$: $h_{III}[M + m] = -h_{III}[M - m], \forall m > 0$

- $\mathbf{a} = M, \mathbf{b} = \frac{\mathbf{p}}{2}$

- $A_{III}(\mathbf{w}) = \sum_{m>0} \{2h[M + m]\sin(m\mathbf{w})\}$

Proof

$$\begin{aligned} \hat{H}_{III}(\mathbf{w}) &= \sum_n h[n] e^{-j\mathbf{n}\mathbf{w}} \\ &= h[M] e^{-jM\mathbf{w}} + \sum_{m>0} \{h[M + m] e^{-j(M+m)\mathbf{w}} + h[M - m] e^{-j(M-m)\mathbf{w}}\} \\ &= e^{-jM\mathbf{w}} \sum_{m>0} \{h[M + m] e^{-jm\mathbf{w}} - h[M - m] e^{+jm\mathbf{w}}\} \\ &= \left[\sum_{m>0} \{2(-j)h[M + m]\sin(m\mathbf{w})\} \right] e^{-jM\mathbf{w}} \\ &= \left[\sum_{m>0} \{2h[M + m]\sin(m\mathbf{w})\} \right] e^{-j\left(M\mathbf{w} + \frac{\mathbf{p}}{2}\right)} \end{aligned}$$

- Odd about $\mathbf{w} = 0$: $A(0 + \mathbf{w}) = -A(0 - \mathbf{w})$
- Odd about $\mathbf{w} = \pi$: $A(\mathbf{p} + \mathbf{w}) = -A(\mathbf{p} - \mathbf{w})$
- Periodic with period 2π : $A(\mathbf{w} + 2\mathbf{p}) = A(\mathbf{w})$

- Type IV
 - $h[n]$
 - Even duration N
 - Odd-symmetric about midpoint $h[m] = -h[m + 1]$:
 $h_{IV}[M + m] = -h_{IV}[M + 1 - m], \forall m > 0$

- $\mathbf{a} = M + \frac{1}{2}, \mathbf{b} = \frac{\mathbf{p}}{2}$

- $A_{IV}(\mathbf{w}) = \sum_{m>0} \left\{ 2h[M+m] \sin \left(\left(m - \frac{1}{2} \right) \mathbf{w} \right) \right\}$

Proof

$$\begin{aligned} \hat{H}_{IV}(\mathbf{w}) &= \sum_n h[n] e^{-jn\mathbf{w}} \\ &= \sum_{m>0} \left\{ h[M+m] e^{-j(M+m)\mathbf{w}} + h[M+1-m] e^{-j(M+1-m)\mathbf{w}} \right\} \\ &= e^{-j\left(M+\frac{1}{2}\right)\mathbf{w}} \sum_{m>0} \left\{ h[M+m] e^{-j\left(m-\frac{1}{2}\right)\mathbf{w}} - h[M+m] e^{+j\left(m-\frac{1}{2}\right)\mathbf{w}} \right\} \\ &= \left[\sum_{m>0} \left\{ 2(-j)h[M+m] \sin \left(\left(m - \frac{1}{2} \right) \mathbf{w} \right) \right\} \right] e^{-j\left(M+\frac{1}{2}\right)\mathbf{w}} \\ &= \left[\sum_{m>0} \left\{ 2h[M+m] \sin \left(\left(m - \frac{1}{2} \right) \mathbf{w} \right) \right\} \right] e^{-j\left(M+\frac{1}{2}\right)\mathbf{w} + \frac{\mathbf{p}}{2}} \end{aligned}$$

- Odd about $\mathbf{w} = 0$: $A(0+\mathbf{w}) = -A(0-\mathbf{w})$
- Even about $\mathbf{w} = \pi$: $A(\mathbf{p}+\mathbf{w}) = A(\mathbf{p}-\mathbf{w})$
- Periodic with period 4π : $A(\mathbf{w}+4\mathbf{p}) = A(\mathbf{w})$
- \mathbf{a} = mid-location of the duration interval
- $\mathbf{b} = \frac{\mathbf{p}}{2}$ when having odd-symmetric $h[n]$ about midpoint(s)

To see this, odd \Rightarrow negative sign in the middle \Rightarrow sin \Rightarrow -j

- $A(0) = 0$ (III and IV) \Rightarrow block DC \Rightarrow bad low-pass filter
- $A(\pi) = 0$ (II and III) \Rightarrow bad high-pass filter
- Type I isn't the best since pass $\mathbf{w} = 0, \pi$

- Cascading g.l.p FIR filters acts as a g.l.p FIR

$$\hat{H}(\mathbf{w}) = \prod_i \hat{H}_i(\mathbf{w}) = \left(\prod_i A_i(\mathbf{w}) \right) e^{-j \left(\sum_i a_i \right) \mathbf{w} + \sum_i b_i}$$

- Adding (“+”) g.l.p FIR filters may not acts as a g.l.p FIR

To see this, consider the symmetry of resulted $h[n]$

Filter Design technique

- Given $\hat{H}_{des}(\mathbf{w})$

- Targeting FIR g.l.p. filters

Frequency-sampling Design

- Find real $h[n]$ FIR g.l.p. filter with duration interval $0 \leq n < N$

$$\text{and } \left| \hat{H} \left(k \frac{2\mathbf{p}}{N} \right) \right| = \left| \hat{H}_{des} \left(k \frac{2\mathbf{p}}{N} \right) \right| \quad 0 \leq k < N$$

(always exist)

- Step

1) Given N

2) Pick filter type according to the magnitude of $\hat{H}_{des}(\mathbf{w})$ around $0, \pi$
 \Rightarrow know α, β

3) Set real $\tilde{A}(\mathbf{w})$ which

- has required symmetry for the targeted filter type

- $\tilde{A}(\mathbf{w}) = |\tilde{A}(\mathbf{w})| = |\hat{H}_{des}(\mathbf{w})|$

4) Get N equations from: $A \left(k \frac{2\mathbf{p}}{N} \right) = \tilde{A} \left(k \frac{2\mathbf{p}}{N} \right)$

Note that we now look at $\tilde{A}(\mathbf{w})$ for $0 < \omega < 2\pi$

5) Do one of the following:

5.1) Solve for $h[n]$ -values from the above N equations, using linear algebra.

5.2) Set $\hat{G}[k] = \tilde{A} \left(k \frac{2\mathbf{p}}{N} \right) e^{-j \left(ak \frac{2\mathbf{p}}{N} + b \right)}$; $0 \leq k < N$

$$h[n] = \frac{1}{N} \sum_{k=0}^{N-1} \hat{G}[k] \mathbf{y}_N^{+nk}; \quad 0 \leq n < N$$

Time-domain least-squares design

- Minimize $\sum_{\ell=0}^{L-1} \left\| \hat{H}(\mathbf{w}_\ell) - \hat{H}_{des}(\mathbf{w}_\ell) \right\|$ for general set of \mathbf{w}_ℓ , $0 \leq \ell < L$; L can $> N$

- Match (approximately) at a general set of \mathbf{w}_ℓ , $0 \leq \ell < L$ not necessarily uniformly spaced \Rightarrow can prioritize matching regions

- Find $h[n]$, $0 \leq n < N$, such that $\sum_{\ell=0}^{L-1} \left| A(\mathbf{w}_\ell) - \tilde{A}(\mathbf{w}_\ell) \right|$ is minimized

- Let $\alpha_\ell = \tilde{A}(\mathbf{w}_\ell)$, $\underline{h} = \begin{pmatrix} h[first] \\ \vdots \\ h[first + \mathbf{h} - 1] \end{pmatrix}$, $\underline{a} = \begin{pmatrix} \mathbf{a}_1 \\ \vdots \\ \mathbf{a}_k \end{pmatrix}$,

$\Gamma_{L \times h}$ = matrix with entries from coefficients on h 's

- \Rightarrow Minimize $\|\Gamma \underline{h} - \underline{a}\|^2 \rightarrow \hat{\underline{h}} = (\Gamma^T \Gamma)^{-1} \Gamma^T \underline{a}$

Weighted time domain least squares filter design

- Given weights $\epsilon_\ell > 0$. LHW
$$\begin{pmatrix} \mathbf{e}_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \mathbf{e}_L \end{pmatrix}$$
- Choose \underline{h} to minimize $\sum_{\ell=0}^{L-1} \mathbf{e}_\ell \|\Gamma \underline{h}\|_\ell - \mathbf{a}_\ell\|^2$ or $(\Gamma \underline{h} - \underline{a})^T \mathbf{E} (\Gamma \underline{h} - \underline{a}) \Rightarrow$

$$\hat{\underline{h}} = (\Gamma^T \mathbf{E} \Gamma)^{-1} \Gamma^T \mathbf{E} \underline{a}$$

Windowing

- Minimize $\frac{1}{2p} \int_{-p}^p |\hat{H}(\mathbf{w}) - \hat{H}_{des}(\mathbf{w})|^2 d\mathbf{w}$ by

Windowing $h_{des}[n]$ with **rectangular** windowing function $\square_L[n] = \begin{cases} 1 & |n| < L \\ 0 & |n| \geq L \end{cases} \Rightarrow$

$$h[n] = \square_L[n] h_{des}[n] = \begin{cases} h_{des}[n] & |n| < L \\ 0 & |n| \geq L \end{cases} = \text{truncated version of } h_{des}[n]$$

Proof Use Parseval Identity:

$$\begin{aligned} \frac{1}{2p} \int_{-p}^p |\hat{H}(\mathbf{w}) - \hat{H}_{des}(\mathbf{w})|^2 d\mathbf{w} &= \sum_{n=-\infty}^{\infty} |h[n] - h_{des}[n]|^2 \\ &= \sum_{n=-(L-1)}^{L-1} |h[n] - h_{des}[n]|^2 + \sum_{|n| \geq L} |0 - h_{des}[n]|^2 \end{aligned}$$

To minimize, set $h[n] = h_{des}[n]$; $-L < n < L$

- $h[n]$ isn't causal \Rightarrow shift it by $(L-1) \rightarrow 0 \leq n < 2L-1$
- $\hat{H}(\mathbf{w}) = \sum_{n=-(L-1)}^{L-1} h_{des}[n] e^{-jn\mathbf{w}} =$ a partial sum of $\hat{H}_{des}(\mathbf{w})$, which is $\sum_{n=-\infty}^{\infty} h_{des}[n] e^{-jn\mathbf{w}}$

$$\hat{\hat{c}}(\mathbf{w}) = \frac{\sin\left(\left(L - \frac{1}{2}\right)\mathbf{w}\right)}{\sin\left(\frac{\mathbf{w}}{2}\right)} = \frac{\sin\left(\frac{N}{2}\mathbf{w}\right)}{\sin\left(\frac{\mathbf{w}}{2}\right)}$$

Proof

$$\sum_{k=0}^{(2L-1)-1} \mathbf{d}[n-k] \xrightarrow{DTFT} e^{-j\frac{2L-1}{2}\mathbf{w}} \left(\frac{\sin\left(\frac{2L-1}{2}\mathbf{w}\right)}{\sin\left(\frac{1}{2}\mathbf{w}\right)} \right)$$

$$\sum_{k=-(L-1)}^{L-1} \mathbf{d}[n-k] \xrightarrow{DTFT} e^{-j(L-1)\mathbf{w}} \left(\frac{\sin\left(\frac{2L-1}{2}\mathbf{w}\right)}{\sin\left(\frac{1}{2}\mathbf{w}\right)} \right) e^{j(L-1)\mathbf{w}} ; \text{ time-shift rule}$$

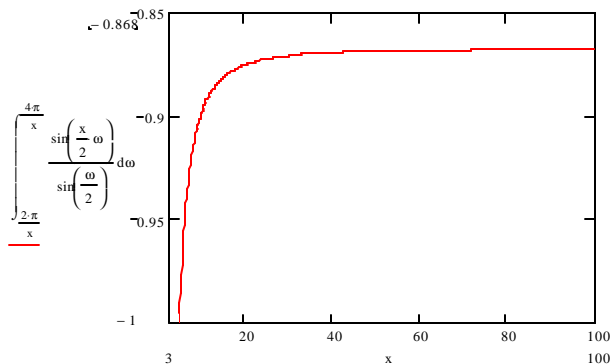
- $\hat{\mathbf{c}}(\mathbf{w}) = \frac{\sin\left(\left(L-\frac{1}{2}\right)\mathbf{w}\right)}{\sin\left(\frac{\mathbf{w}}{2}\right)} = 0$ iff $\left(L-\frac{1}{2}\right)\mathbf{w} = m\mathbf{p}, m \neq 0 \Rightarrow$

$$\mathbf{w} = \frac{m\mathbf{p}}{L-\frac{1}{2}} = \frac{2m\mathbf{p}}{N}, m \neq 0$$

- Central lobe's width = $\frac{2\mathbf{p}}{L-\frac{1}{2}} = \frac{4\mathbf{p}}{2L-1} = \frac{4\mathbf{p}}{N} \Rightarrow$ decrease as N increase

- Area under one side of first side-lobe = $\int_{\frac{\mathbf{p}}{L-\frac{1}{2}}}^{\frac{2\mathbf{p}}{L-\frac{1}{2}}} \frac{\sin\left(\left(L-\frac{1}{2}\right)\mathbf{w}\right)}{\sin\left(\frac{\mathbf{w}}{2}\right)} d\mathbf{w} = \int_{\frac{2\mathbf{p}}{N}}^{\frac{4\mathbf{p}}{N}} \frac{\sin\left(\frac{N}{2}\mathbf{w}\right)}{\sin\left(\frac{\mathbf{w}}{2}\right)} d\mathbf{w}$

\Rightarrow roughly the same @ -0.868 as N increases



- $h[n] = \square_L[n] h_{des}[n] \xrightarrow{DTFT} \hat{H}(\mathbf{w}) = \frac{1}{2\mathbf{p}} \int_{-\mathbf{p}}^{\mathbf{p}} \hat{H}_{des}(\mathbf{m}) \hat{\mathbf{c}}(\mathbf{w}-\mathbf{m}) d\mathbf{m}$

- $\hat{H}(\mathbf{w}) = \frac{1}{2\mathbf{p}} \int_{-\mathbf{p}}^{\mathbf{p}} \hat{H}_{des}(\mathbf{m}) \hat{\mathbf{c}}(\mathbf{w}-\mathbf{m}) d\mathbf{m}$

Start with $\mathbf{w} = 0$ and increasing it.

Assume that the side lobes beyond the first one don't contribute too much.

- First, central and two first-side-lobe of $\hat{c}(w - m)$ is in the passband of $\hat{H}_{des}(m)$, so $\text{integral} \approx \left(\text{area under main lobe} \right) - 2 \left(\text{area under first-side-lobe} \right)$
- Next, the right first-side-lobe is going out of $\hat{H}_{des}(m)$'s passband so the integral increase until all of the right first-side-lobe is gone out of $\hat{H}_{des}(m)$'s passband. Then, $\text{integral} \approx \left(\text{area under main lobe} \right) - \left(\text{area under (left) first-side-lobe} \right)$
so, height of the overshoot is proportional to the area of the first-side lobe
- Then, Central lobe start going out of $\hat{H}_{des}(m)$'s passband so the integral start to decrease again (big decrease). This is where the transition region occurs and it is proportional to the width of the main lobe.
- Finally, all of the main lobe is gone out of $\hat{H}_{des}(m)$'s passband. The left first-side lobe starts to get out, so the integral increases again because less negative part is included.
- Gibbs Phenomenon (9% overshoot) at jump
- Bigger N \Rightarrow narrower central lobe \Rightarrow narrower transition region
- Same first-side-lobe area \Rightarrow same peak overshoot (Gibbs); $\forall N$

	$\square_L[n]$ for $-L < n < L$ (= 0 for $ n \geq L$)	$\frac{4p}{N}$	- G
5 HWQ XDU		$\frac{4p}{N}$	- G
7 UDQ XDU %DUWVW	$\frac{ n }{L}$	$\frac{8p}{N}$	- G
+DQQ +DQQQ	$\frac{1}{2} + \frac{1}{2} \cos \frac{np}{2}$	$\frac{8p}{N}$	- G
Hamming	$.54 + .46 \cos \frac{np}{2}$	$\frac{8p}{N}$	- G

0 IQP D) ICMUGHMJQ

- w_c = cutoff
 w_p = last $w < w_c$ (in passband) where $\hat{H}(w) = 1$
 w_s = first $w > w_c$ (in stopband) where $\hat{H}(w) = 0$
 $w_s - w_p \sim$ transition region width
 d_I = passband ripple max
 d = ripple max

- 3URVMS LHSUREOP
 - DHMJ QDGXUDWRQ -1), 5 IICMU
 - transition region width $\omega_s - \omega_p <$ a specific amount
 - minimizes the maximum of d_1 and d_2
- 3URSHUWARI VRCXWRQ
 - Equiripple in both passband and stopband
 - $d_1 = d_2$
 - number of ripples between 0 and ω_c is N
 - ELJHUJ \Rightarrow P DDUU $d_1 = d_2$ UHSSON

Signal flow graph

- Any signal flow graph describing filter is a realization of the filter
- Minimal/canonical realization \Rightarrow fewest possible delay branch “ $\xrightarrow{z^{-1}}$ ”
- #delay branches \approx amount of memory required via the given signal flow graph

- In general, $H(z) = \frac{p(z)}{q(z)} = \underbrace{p(z)}_{FIR} \underbrace{\left(\frac{1}{q(z)}\right)}_{IIR}$, a proper rational function

- Order of the filter = degree of $q(z) = N$ (assume fraction is in lowest terms)
 - Ex.
- Filter is FIR $\Leftrightarrow q(z) = z^n$
- Minimal realization have # delay branches = Order of the filter = N
- $y[n] + a_1 y[n-1] + a_2 y[n-2] = b_0 w[n] + b_1 w[n-1] + b_2 w[n-2]$

$$H(z) = \frac{b_0 z^2 + b_1 z + b_2}{z^2 + a_1 z + a_2} \Rightarrow N=2$$

Direct Form II: Controllable canonical realization

- $Y(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 + a_1 z^{-1} + a_2 z^{-2}} W(z) = (b_0 + b_1 z^{-1} + b_2 z^{-2}) \underbrace{\left(\frac{W(z)}{1 + a_1 z^{-1} + a_2 z^{-2}}\right)}_{Q(z)}$

- $Q(z) = \frac{W(z)}{1 + a_1 z^{-1} + a_2 z^{-2}}$

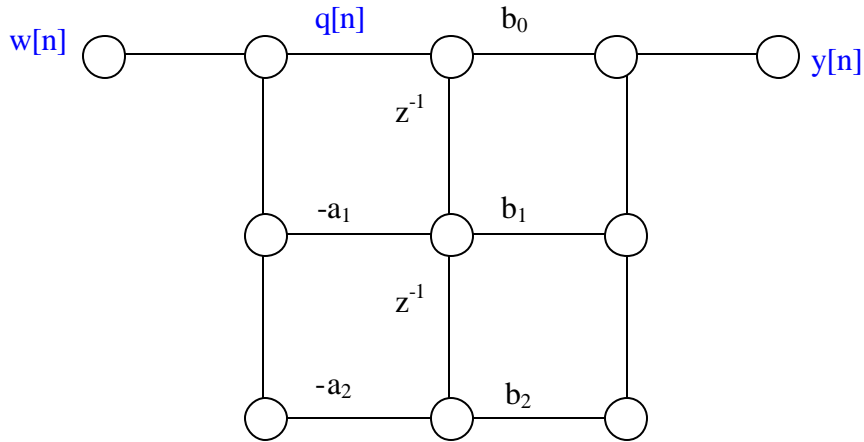
$$Q(z) + a_1 z^{-1} Q(z) + a_2 z^{-2} Q(z) = W(z)$$

$$q[n] + a_1 q[n-1] + a_2 q[n-2] = w[n]$$
- $q[n] = w[n] - a_1 q[n-1] - a_2 q[n-2]$

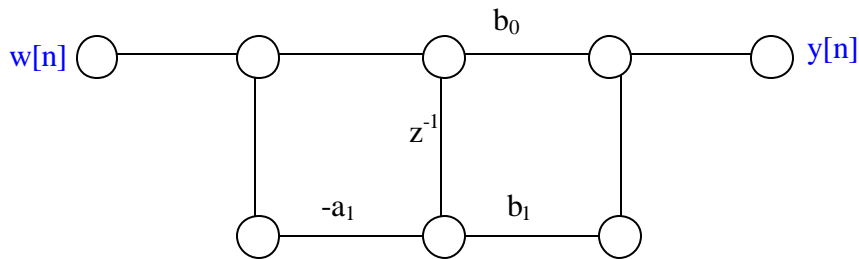
$$Y(z) = (b_0 + b_1z^{-1} + b_2z^{-2})Q(z)$$

$$Y(z) = b_0Q(z) + b_1z^{-1}Q(z) + b_2z^{-2}Q(z)$$

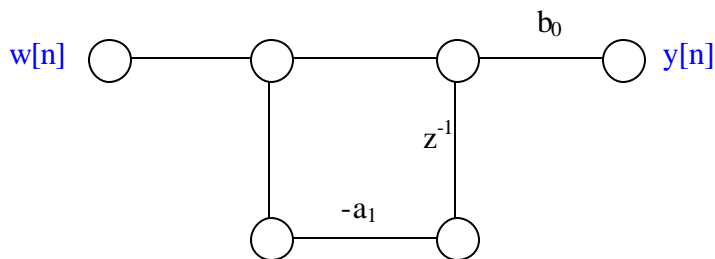
$$y[n] = b_0q[n] + b_1q[n-1] + b_2q[n-2]$$



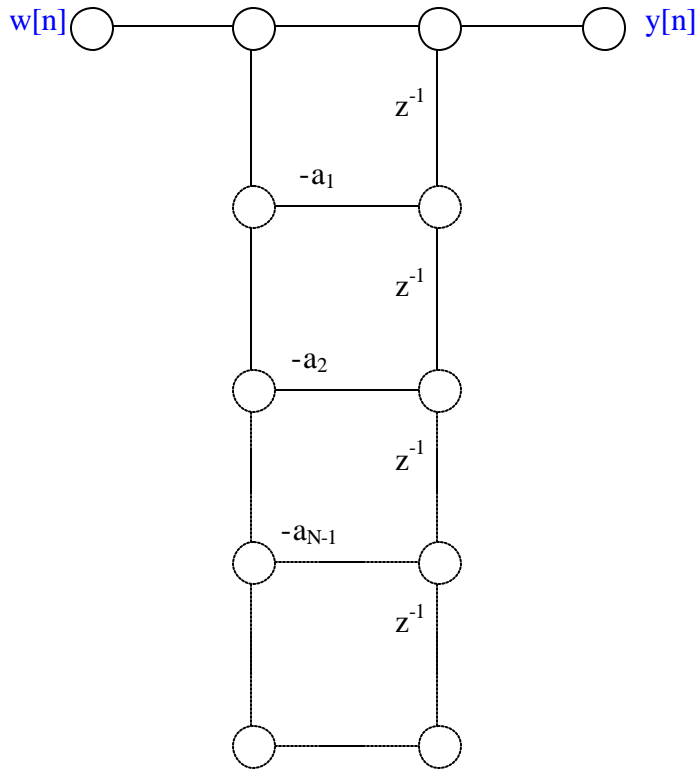
- $H(z) = \frac{b_0z + b_1}{z + a_1} = \frac{b_0 + b_1z^{-1}}{1 + a_1z^{-1}}$



- $H(z) = \frac{b_0z}{z + a_1} = \frac{b_0}{1 + a_1z^{-1}}$

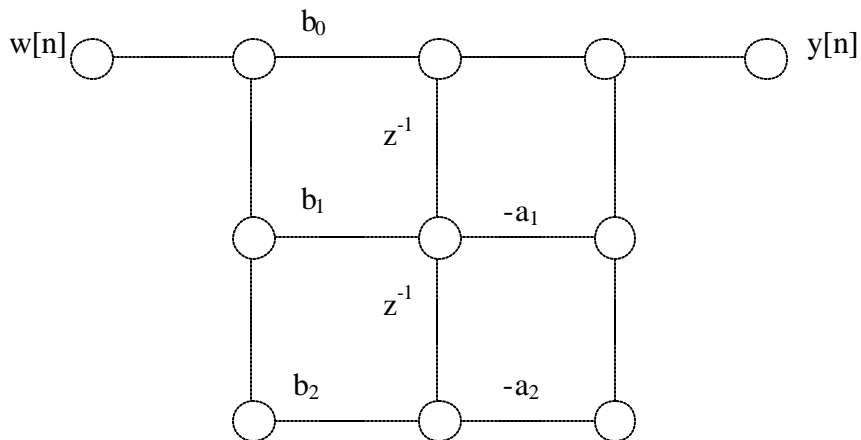


- $H(z) = \frac{1}{1 + a_1z^{-1} + \dots + a_Nz^{-N}}$



Transposed Direct Form II: Observable canonical realization

- $y[n] = b_0 w[n] + (b_1 w[n-1] - a_1 y[n-1]) + (b_2 w[n-2] - a_2 y[n-2])$

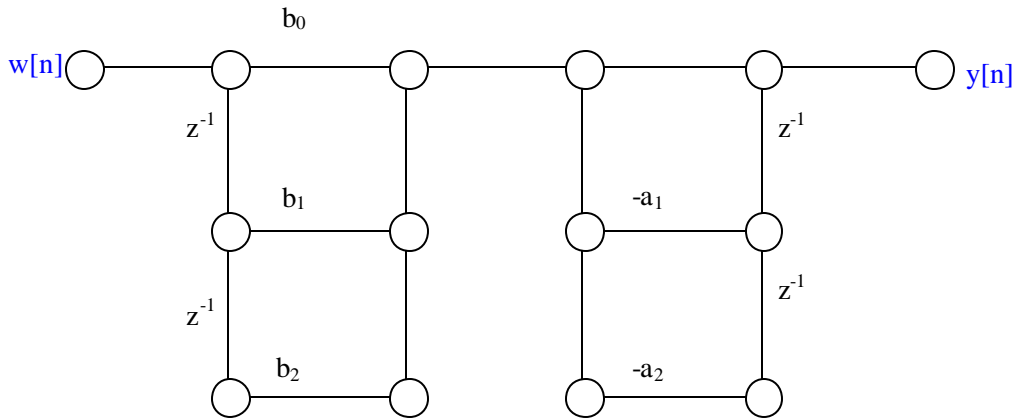


- Guarantees that it also realizes $H(z)$
- To get from direct form II, just reverse all the arrows and switch roles of $w[n]$ and $y[n]$

' ICHVRCP ,

- CRQP IQP DCHDQ DWRQ
- $g[n] = b_0 w[n] + b_1 w[n-1] + b_2 w[n-2] = y[n] + a_1 y[n-1] + a_2 y[n-2]$

$$y[n] = g[n] - a_1 y[n-1] - a_2 y[n-2]$$



- **Cascade Realization** : a chain of direct form realizations of the individual 1st- and 2nd- order factors

- **3DUMMURUP**

- $(\text{[SDQG } \frac{H(z)}{z} \text{ XM SDUWODFWRCV})$

- $5 \text{ HDJ HFDKSLFHGLUFW}$

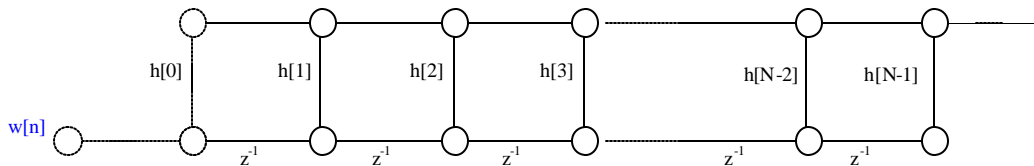
- HRRNXS IQSDHOD

- **Cascade of an FIR system with an IIR system**

$$H(z) = \frac{p(z)}{q(z)} = \underbrace{p(z)}_{\text{FIR}} \underbrace{\left(\frac{1}{q(z)} \right)}_{\text{IIR}}$$

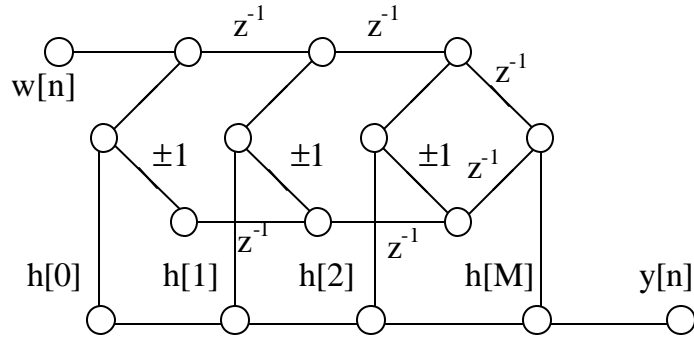
- (Causal) **FIR Filters**

- $h[n] = \sum_{k=0}^{N-1} h[k] w[n-k]; H(z) = \sum_{k=0}^{N-1} h[k] z^{-k}; y[n] = \sum_{k=0}^{N-1} h[k] w[n-k]$



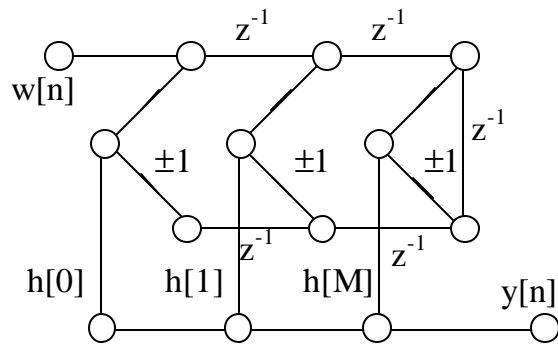
- FIR filters with generalized linear phase

-) RU RCG , , ,



use -1 for odd symmetric $h[n]$ (III)

-) RU FMQ ,, ,9



use -1 for odd symmetric $h[n]$ (IV)